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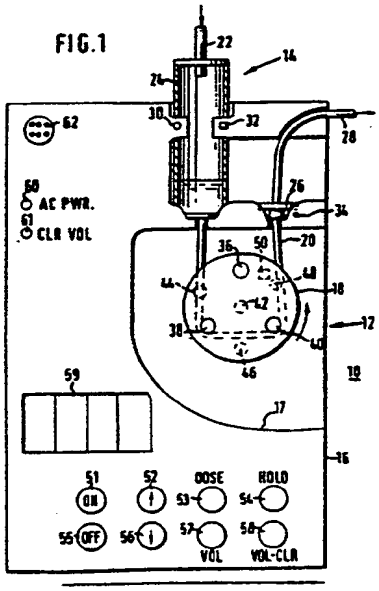
(54) Motor unit for a fluid pump and method of operation.

(57) An enteral nutrition pump system (10) operates in a cyclical manner with a period between cycles being selected in accordance with the desired fluid delivery rate. Each pump cycle may correspond to a single rotation of the rotor (18) or a fractional rotation of the rotor. Rotor rotation may alternatively be sensed by utilization of magnetic sensors (50) or by monitoring of the AC component of current supplied to a DC motor driving the rotor.

FIG.1



EP 0 327 209 A2

MOTOR UNIT FOR A FLUID PUMP AND METHOD OF OPERATION

This invention relates to pumps for delivering medical fluids and particularly relates to peristaltic pumps for delivery of enteral nutrition fluids to a patient.

In accordance with known techniques the delivery of enteral nutrition fluids to a patient can be accurately controlled as to volumetric delivery rate by the use of a delivery system which includes a motor unit and a disposable delivery set. Likewise similar systems may be used for pumping of other fluids for medical purposes, such as intravenous infusion, blood pumping or supply of measured volumes of liquid medication to pre-loaded syringes or other containers.

In known systems for delivering enteral fluids the rate of fluid delivery is controlled by regulating the speed of a pump motor in accordance with the desired volume rate. Pump motor speed may be controlled, for example, by providing pulses to a stepper motor. Another system for providing variable-rate fluid delivery makes use of a peristaltic pump with variable tension on the pump tube in combination with a constant speed motor.

In other known systems for pumping medical fluids there are provided means for monitoring rotation of the pump rotor, for example, by magnetic detection or by optical rotation detectors. In such systems the actual rotation rate of the motor is compared to the desired rotation rate for purposes of making corrections to the rotation rate of the motor. Alternately the motor may be operated to rotate the pump by a number of rotations corresponding to the desired volume.

It is an object of the present invention to provide a new and improved method for regulating the volumetric rate of fluid delivery in a medical fluid delivery system and to provide apparatus for carrying out the improved method.

In accordance with the present invention there is provided a motor unit for a medical fluid delivery system for use with a disposable delivery set for pumping medical fluid, characterised in that it comprises: pump operating means, including a motor, for acting in cooperation with the delivery set to deliver a volume of the fluid during each operating cycle;

and pump control means for controlling the pump operating means to deliver the fluid at a desired volumetric rate, the pump control means including means responsive to signals indicating the desired rate for activating the pump operating means for one of the operating cycles and for repeating the activation at variable time intervals selected in accordance with the desired volumetric rate.

In accordance with a preferred embodiment of the invention the pump operating means is a pump rotor for operating in connection with a pump tube on the delivery set to form a peristaltic pump and the pump operating cycle comprises a selected angular rotation of the pump rotor. In one arrangement the pump control means includes means for sensing the condition of the pump operating means with respect to an operating cycle, and the sensing means comprise a magnet and a magnetic field sensor. In another arrangement the sensing means may detect the AC component of the current supplied to a DC motor.

The medical fluid delivery system which comprises the novel motor unit and a disposable fluid delivery set carries out a novel method for controlling the rate of fluid delivery. The novel method includes providing means for detecting the completion of an operating cycle of the pump operating means and operating the motor unit until the completion of the operating cycle is detected. Operation of the motor unit is repeated at variable time intervals which are selected in accordance with the desired rate of fluid delivery.

In accordance with another aspect of the present invention the AC component of the DC motor current is detected and compared to a reference level in order to detect the current variation which results from the presence of a pump tube on the rotor. Accordingly, any mis-installation of the pump tube will be detected by the fluid delivery pump.

For a better understanding of the present invention, together with other and further objects, reference is made to the following description, taken in conjection with the accompanying drawings, in which:

Figure 1 is a plan elevation view of an enteral fluid delivery system incorporating the present invention.

Figure 2 (comprising Figures 2a, 2b and 2c) is a circuit diagram for the system of Figure 1.

Figure 3 is a circuit diagram for a portion of a modified delivery system in accordance with the present invention.

Figure 4 is a timing diagram illustrating signals utilized in the present invention.

Figure 1 is an illustration of an enteral fluid delivery system incorporating a motor unit in accordance with the present invention. The enteral delivery system 10 includes a motor unit 12 and a disposable delivery set generally indicated as 14 which is arranged to be mounted on the motor unit. The motor unit 12

includes a housing 16, which in the illustrated embodiment includes a recess 17 within which a rotor 18 is mounted. Rotor 18 is driven by a conventional constant speed DC motor which drives shaft 42. The delivery set 14 includes a pump tube 20, made of flexible plastic which surrounds rotor 18 and interacts with 3 rollers 36, 38 and 40 mounted on rotor 18 to form a peristaltic pump. Rotation of the rotor 18 in the direction indicated by the arrow in Figure 1 causes the rollers 36, 38 and 40 to interact with pump tube 20 and pump fluid through the tube at a rate which is determined by the rate rotation of rotor 18.

Delivery set 14 includes an inlet tube 22, which is connected to a supply of enteral fluids, such as a fluid reservoir which may be mounted on an IV pole above the motor unit 12. The inlet tube 22 is connected to drip chamber 24 which is mounted to a recess on housing 16 and secured to one end of pump tube 20. The outlet end of pump tube 20 is provided with a mounting member 26 which is received in another recess on housing 16 to thereby secure the outlet end of tube 20. A fluid delivery tube 28 is connected to mounting member 26 and supplies fluid pumped by the system to an enteral feeding tube connected to a patient or to another medical fluid delivery system.

The system illustrated in Figure 1 additionally includes a light source 30 and a light detector 32 for operation in connection with drip chamber 24 to detect the occurrence of drops in the drip chamber which pass between light source 30 and detector 32 in a manner which is known in the art. Mouting member 26 includes magnetized material, the presence of which can be detected by magnetic field detector 34.

The motor unit 12 includes control buttons 51 through 58 for operating the unit to turn it on or off, to set the dose or volume rate of fluid delivery by the pump, to interrupt operation of the pump and to increase or decrease the designated fluid volume or volume rate. A four digit alphanumeric segment display 59 is provided for indicating the selected fluid delivery rate or delivered volume and for providing alarm messages or codes. Light emitting diode 60 and 61 are provided for indicating that the unit is plugged into AC power or indicating that the volume setting has been cleared. An enunciator 62 is provided for signalling an audible alarm to indicate, for example, that the pump has completed delivering a designated volume of fluid.

Housing 16 is provided with a magnetic field sensor 50 which is arranged adjacent and behind rotor 18 in order to detect the magnetic field provided by magnets 44, 46 and 48 which are mounted on rotor 18. The presence of the magnets 44, 46 and 48 is detected as the magnets pass sensor 50 during rotation of rotor 18.

Figure 2 is a schematic diagram of the circuits in the pump motor unit 12 of Figure 1. The schematic representations of the various components of Figure 1 have been given same reference numerals in Figure 2.

The motor unit operates under the control of a microcomputer 64 which is provided with a control program which is set forth in Appendix I. A programmable interval timer 68 is provided for operating and initiating microcomputer 64. A clock 66, operating at 2 Mhz, provides clock pulses to the system. The various controls of the unit, 51 through 58, are provided as input signals which ground various input terminals of the microcomputer to thereby signal the operators input instructions. The alphanumeric display 59 is driven by the microcomputer as is LED indicator 61. Additional inputs to the microcomputer are provided by the magnetic field sensors 34 and 50 which sense respectively the magnetized mounting member 26 and the magnets 44, 46 and 48 on rotor 18. Likewise the drop detector 30, 32 is connected to provide input signals to the microcomputer. An AC power rectifier 72 is provided for AC operation and battery charging. Portable DC operation is available using battery 74. The AC circuit is arranged to charge the DC battery when the unit is connected to AC power. A low battery and dead battery detector circuit 70 is provided to signal the microcomputer that the battery needs recharging. The microcomputer provides an output motor signal which is coupled by transistor 80 to switching transistors 82, 84. Transistor 82 turns on the power supply to motor voltage regulator 88 when the motor is to be operated and transistor 84 short circuits the motor to lock it into position when the motor signal is no longer present. Switching transistor 78, which is provided with a power signal by transistor 76, operates to supply current to the motor system and the other electronic systems by voltage regulator 86 when power is turned on. The motor 90 is provided with a safety circuit 92 which provides a short circuit when the motor is operated for an excess period of time. The short circuit causes fuse 94 to open thereby disabling the set when continuous motor operation occurs, to avoid providing excess enteral fluid to a patient.

Unlike conventional enteral nutrition systems the system 10 of the present invention is designed to provide an intermittent motor operation with the periodicity of the intermittent operation being regulated to adjust to the desired rate of fluid delivery. The operation of the system of the present invention is therefore cyclical and will be explained with respect to timing diagrams of Figure 4. Graph A of Figure 4 illustrates the motor voltage of the enteral fluid delivery system 10. The motor voltage is turned on and operated for a time period G which is regulated by detecting the rotation of rotor 18, in the case of Graph A for one

complete revolution. With reference to Figure 1 it may be seen that during one complete revolution, represented by motor voltage period G, three magnets 44, 46 and 48 all pass magnetic field detector 50 and are sensed thereby. Curve B in Figure 4 illustrates the output signal from the rotor sensing magnetic field detector 50 which occurs during the cycle of operation indicated by motor voltage G. During an initial period of approximately .45 seconds designated F in Figure 4 the operation of the rotor sensing is inhibiting by software in microcomputer 64, so that the initial on period J of magnetic field detector 50 is not responded to by the program. Thereafter, during one complete revolution of the rotor, the signal from detector 50 goes to zero as each magnet is encountered by detector 50. Upon detection of the third magnet, at the end of period G, the motor voltage is turned off. In accordance with the preferred embodiment of the present invention the unit repeats the cyclical operation a time period I after initiation of the first operation. The time period H during which there is provided no motor voltage is permitted to be variable, since it depends on the actual time taken for rotation of the rotor and the selected interval I. The interval I is selected according to the rate of fluid delivery to be provided by the set which is set by the operator. In one embodiment of the invention period I varies from 13.5 seconds corresponding to a delivery rate of 100 milliliters per hour to 4.5 seconds corresponding to a fluid delivery rate if 300 milliliters per hour. Motor operation period G takes approximately 4 seconds but may vary according to mechanical conditions of the motor and pump tube.

Graph E in Figure 4 shows an alternate timing arrangement wherein the motor cycle consists of a single one-third of a rotation of the rotor 18. In accordance with the operation method of Graph E the motor current period G' is ended by the detection of the first of the three circumferentially arranged magnets by magnetic field sensor 50. Again the timing I between each operating cycle of the motor is varied in order to control volumetric fluid rate delivered by the pump. In the same embodiment as previously discussed a fluid rate of 1 to 100 milliliters per hour can be delivered using a cycle interval I which ranges from 450 to 4.50 seconds.

As an alternate, or in addition to providing magnets on rotor 18 for purposes of detecting completion of a motor cycle, the motor current may be monitored for purposes of determining the rotational position of the rotor 18. Figure 3 is a schematic diagram of a circuit wherein there is provided a motor current monitoring circuit 96 which includes a low resistance resistor in series with the motor the voltage across which is AC coupled to an AC amplifier 92 for purposes of monitoring the AC component of the DC motor current. Graph C of Figure 4 illustrates a typical motor current for the operating cycle of Graph A of Figure 4. The motor current initially rises to a high level for purposes of overcoming the starting resistance and accelerating rotor 18 to its normal velocity. Thereafter the motor current drops but reaches periodic peaks corresponding to the resistance of rollers 36, 38 and 40 as they stretch pump tube 20 to its furthest position. The peak periods of motor current, which are illustrated as negative going pulses in the digitized signal of curve D, which is the output at point 96 of the circuit of Figure 3, may be used for purposes of detecting rotor position and may be used also for assuring that the pump tube 20 is properly mounted to rotor 18. Because of the initially high rotor current, which results from starting up the rotor, the current sensing is software inhibited for time period K of approximately .25 seconds prior to initiating the threshold detection which results in the pulses of curve D. Each of the pulses illustrated in curve D, which are negative going, have a positive going pulse which occurs a time period L prior to the end of a motor cycle, there being three such pulses during one rotation of the rotor. Accordingly, the curve D signal can be used for purposes of detecting and monitoring rotation position of rotor 18, and thereby indicating to the motor control circuit the completion of an operating cycle. As an alternate to providing delay L after the end of the curve D pulses, the motor cycle may be arranged to end at the end of the pulse, providing a different rotor position between cycles.

The motor current monitoring previously described can additionally be used in cases wherein the motor voltage is provided only for a one-third rotation of the rotor as discussed with respect to curve E.

An additional use of the motor current monitoring circuit, which provides the signal of curve D of Figure 4 is to provide assurance to the system that the pump tube 20 has been properly mounted on rotor 18. Accordingly at the initiation of motor current and after a delay period K a flag can be set by the microprocessor which is cleared by the negative going pulse of curve D to indicate proper pump tube positioning. The flag would be reset at the start of each operating cycle or may also be reset on the occurrence of the one-third rotation of the rotor sensing current shown by curve B. If the flag is not cleared by the negative going pulse of curve D there is an indication that either there is no pump tube or that the pump tube has been improperly mounted and an alarm signal can be initiated.

Claims

1. A motor unit for a medical fluid delivery system for use with a disposable delivery set for pumping medical fluid, characterised in that it comprises:
pump operating means, including a motor, for acting in cooperation with the delivery set (14) to deliver a volume of the fluid during each operating cycle;
and pump control means for controlling the pump operating means to deliver the fluid at a desired volumetric rate, the pump control means including means responsive to signals indicating the desired rate for activating the pump operating means for one of the operating cycles and for repeating the activation at variable time intervals selected in accordance with the desired volumetric rate.

2. A motor unit as claimed in claim 1 wherein the pump operating means comprises a pump motor (18) for acting in cooperation with a pump tube (20) on the delivery set (14) and wherein the operating cycle comprises a selected angular rotation of the pump rotor.

3. A motor unit as claimed in claim 1 or 2 wherein the pump control means includes means for sensing the condition of the pump operating means with respect to the operating cycle.

4. A motor unit as claimed in claim 3 wherein the means for sensing comprises at least one magnet (44, 46, 48) and a magnetic field sensor (50).

5. A motor unit as claimed in claim 3 wherein the pump operating means comprises a DC motor and wherein the means for sensing the condition of the pump operating means comprises means for sending the AC component of the current supplied to the DC motor.

6. A motor unit for a medical fluid delivery system for use with a disposable delivery set having a flexible pump tube for engagement with the motor unit for pumping medical fluids, characterised in that it comprises:
a housing (16) for receiving at least portions of the delivery set (14);
a motor driven rotor (18) mounted on the housing (16) for rotational movement with respect thereto and for receiving the flexible pump tube (20) for forming a peristaltic pump;
at least one magnet (44, 46, 48) and at least one magnetic field detector (50) mounted to the rotor (18) and the housing (16) for relative rotational motion with respect to each other, the magnet and the magnetic field detector being operatively adjacent to each other at at least one rotational position of the rotor;
and pump control means, responsive to selection of a fluid delivery rate and responsive to the magnetic field detector (50), for operating the motor until the rotor is in the rotation position with the magnet and the magnetic field detector adjacent each other and for repeating the operation at variable time intervals selected in accordance with the selected fluid delivery rate.

7. A motor unit for a medical fluid delivery system for use with a disposable delivery set having a flexible pump tube for engagement with the motor unit for pumping medical fluids, characterised in that it comprises:
a housing for receiving at least portions of the delivery set;
a rotor driven by a DC motor, mounted on the housing for rotational motion with respect thereto and for receiving the flexible pump tube for forming a peristaltic pump;
means for sensing the AC component of the current supplied to the DC motor thereby to sense rotation of the rotor by an incremental amount corresponding to an incremental volume of pumped fluid;
and pump control means, responsive to selection of a fluid delivery rate and responsive to the current sensing means, for operating the motor until the incremental rotation is sensed and for repeating the operation at variable time intervals selected in accordance with the selected fluid delivery rate.

8. A method for controlling the rate of fluid delivery in a medical fluid delivery system comprising a motor unit and a disposable fluid delivery set for mounting to the motor unit to form a pump, and wherein the motor unit is adapated to act on the fluid delivery set in repeated operating cycles to deliver a volume of fluid for each cycle and means are provided for detecting the completion of the operating cycle, which method comprises:
operating the motor unit until the completion of the operating cycle is detected;
and repeating operation of the motor unit at time intervals selected in accordance with the desired rate of fluid delivery.

9. A method as claimed in claim 8 for further controlling the volume of fluid delivered comprising counting the number of the operating cycles and interrupting the repeating operation when a number of the operating cycles corresponding to a desired volume has been completed.

10. A method for controlling the rate of fluid delivery by a fluid delivery system comprising a motor unit and a disposable delivery set, wherein the pump unit includes a motor driven rotor for engaging a flexible pump tube on the delivery set to form a peristaltic pump and wherein at least one magnet is provided on

the rotor and a magnetic field detector is provided on the pump unit at a position adjacent the magnet in one rotational position of the rotor, which method comprises:
operating the pump unit to rotate the rotor until the magnetic field detector detects the magnet; and
repeating the operating step at a variable time interval selected according to the desired delivery rate of the delivery system.

11. A method as claimed in claim 10 wherein there are provided a plurality of the magnets equally angularly spaced on the rotor and wherein the operating step comprises operating the pump unit until the magnetic field detector detects a selected number of the magnets.

12. A method as claimed in claim 10 or 11 wherein the operating step further includes the step of inhibiting operation of the magnetic field detector for a selected time.

13. A method for controlling the rate of fluid delivery by a fluid delivery system comprising a motor unit and a disposable delivery set, wherein the pump unit includes a rotor driven by a DC motor for engaging a flexible pump tube on the delivery set to form a peristaltic pump, which method comprises:
detecting the AC component of the DC current and forming digital pulses representative thereof;
operating the pump unit to rotate the rotor until a selected number of the digital pulses occur; and
repeating the operating step at a time interval selected according to the desired delivery rate of the delivery system.

14. A method as claimed in claim 13 wherein the operating step further includes a step of inhibiting the AC detecting step for a selected time.

15. A method for detecting the absence of a pump tube on the rotor in a fluid delivery system comprising a motor unit and a disposable delivery set, wherein the pump unit includes a DC motor driven rotor for engaging a flexible pump tube on the delivery set to form a peristaltic pump, which method comprises:
detecting the AC component of the current provided to the DC motor;
comparing the detected AC component of the current to a reference level thereby to detect current variation resulting from the presence of a pump tube on the rotor.

```
Avocet 6805 Assembler v1.12, #01040    Chip=6305                    12/18/87   16:08:57
K224/324  PUMP

 1      $CHIP(6305)
 2      $pagewidth=132
 3      $PAGINATE
 4      $TITLE(K224/324 PUMP)
 5      $XREF
 6      ;=================================================================
 7      ;
 8      ;       This file contains the software for the K224/K324 series of
 9      ;       Enteral Feeding Pumps. It is based on COMBO2.ASM a combined
10      ;       F1500 and K224 program. See COMBO2.ASM for revision history.
11      ;
12      ;=================================================================
13      ; FILE NAME= KPMP31.ASM
14      ;-----------------------------------------------------------------
15      ;   DATE    | REVISION |         DESCRIPTION
```

```
16      ;-------------------------------------------------------------------
17      ;
18      ;  12/04/87 |    031.0 |  DISPLAY LEADING ZERO'S IN DOSE MODE.
19      ;           |          |  CHECK FOR DROPS CONTINUOSLY IN RUN MODE
20      ;           |          |  WHEN RATE IS < 100 ML/HR.
21      ;-------------------------------------------------------------------
22      ;
23      ;  11/24/87 |    030.0 |  ADD NOPS TO IR TEST DURING TESTD.
24      ;           |          |  CLEAR TESTD FLAG WHEN OFF MODE IS ENTERED TO
25      ;           |          |  ALLOW PUMP TO DISABLE IF NECESSARY.
26      ;           |          |  CLEAR VOL MODE FLAG WHEN LO BAT IS ENTERED
27      ;           |          |  LOCK-OUT HOLD/START AND VOL BUTTONS WHEN
28      ;           |          |  INC OR DEC BUTTONS ARE PRESSED.
29      ;           |          |  FIX CLR VOL LED ERROR
30      ;           |          |  CHECK DEC BUTTON BEFORE INC BUTTON.
31      ;           |          |  ADD DELAY TO INC AND DEC BUTTON IN DOSE MODE TO
32      ;           |          |  ALLOW TIME FOR doSE DISPLAY.
33      ;-------------------------------------------------------------------
34      ;
35      ;  11/11/87 |    029.0 |  CHANGE PUMP ID FROM PORTD(1), TO PORTB(6).
36      ;-------------------------------------------------------------------
37      ;
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38      ;  10/23/87 |    028.0 |  FIXED 24 HOUR TIME ERROR. PUMP WAS TIMING 21 HOURS
39      ;             |          |  MODIFIED SO THAT PUMP DISABLES AFTER 24 HOURS
40      ;             |          | WHEN ON AC OR BATTERY POWER.
41      ;-------------------------------------------------------------------------
42      ;
43      ;  10/16/87 |    027.0 |  CHANGED SETCK ROUTINE TO TEST FOR SET WHENEVER
44      ;             |          |  PUMP IS IN RUN MODE. OLD VERSION ONLY CHECKED
45      ;             |          |  WHEN MOTOR IS RUNNING.
46      ;             |          |  RATE CHECK FOR 324 IS DISABLED DURING TEST MODE.
47      ;             |          |  DISABLE DOSE BUTTON WHILE INC OR DEC BUTTONS
48      ;             |          |  ARE PRESSED.
49      ;-------------------------------------------------------------------------
50      ;
51      ;  10/13/87 |    026.0 |  ADD RECHECK OF PUMP ID DURING TESTD
52      ;             |          |  ADDED DELAY FROM MOTOR TURN-ON TO DEAD BAT ROUTINE
53      ;             |          |  CHANGED LOW BAT ROUTINE SO IT KILLS POWER IF
54      ;             |          |  LO BAT OCCURS WHEN UNIT IS ALREADY OFF.
55      ;             |          |  CHANGE POLARITY OF AC DETECT LINE. (REV 7 BOARD)
56      ;-------------------------------------------------------------------------
57      ;
58      ;  10/13/87 |    025.0 |  CORRECTED ERROR IN 1/2 SEC TIMER..
59      ;             |          |  ADDED DOSE DEL CHECK PRIOR TO RUN MODE
```

```
60      ;-------------------------------------------------------------------
61      ;
62      ;  10/12/87 |    024.0 |  ADD NOPS IN DROPCK BETWEEN IR TURN-ON AND
63      ;           |          |  TEST TO ALLOW FOR SETTLING.
64      ;           |          |  SHORTED IR ON TIME.
65      ;           |          |  MOVE DROPCK FROM 8 MS TO 2 MS TO IMPROVE
66      ;           |          |  DROP DETECTION.
67      ;-------------------------------------------------------------------
68      ;
69      ; 10/10/87  |    023.0 |   DEL STOP INSTR. FROM EACH DISABLE ROUTINE.
70      ;           |          |  BLANK ALL DIGITS IN EACH DISABLE ROUTINE.
71      ;-------------------------------------------------------------------
72      ;
73      ; 10/07/87  |    022.0 |  THE RESET ROUTINE HAS BEEN MODIFIED TO KEEP
74      ;           |          |  THE PUMP OFF. TURN-ON IS NOW ACCOMPLISHED IN
75      ;           |          |  THE INT ROUTINE. CHANGE WAS MADE TO PREVENT STRAY
76      ;           |          |  RESEST SIGNALS FROM WATCHDOG FROM ACCIDENTLY
77      ;           |          |  TURNING PUMP ON DURING DISABLE SEQUENCE.
78      ;-------------------------------------------------------------------
79      ;  9/29/87  |    021.0 |  REVISED THE DISABLE ROUTINES TO DISABLE INT
80      ;           |          |  AND LOOP UNTIL POWER DISSIPATES.
81      ;-------------------------------------------------------------------
```

```
82      ;
83      ;  9/22/87  |    020.0 |  TEST ROUTINE HAS BEEN ADDED. IT IS INITIATED BY
84      ;           |          |  PRESSING THE OFF AND HOLD BUTTONS DOWN AT THE
85      ;           |          |  SAME TIME FOR APPROX. 3 SEC WHEN PUMP IS OFF.
86      ;
87      ;  9/22/87  |    019.0 |  MOTOR CONTROL SIGNAL POLARITY HAS BEEN REVERSED
88      ;           |          |  AND TEST MODE WAS CHANGED SO THAT CLR VOL LED
89      ;           |          |  IS TURNED OFF WHEN BUZZER IS.
90
91      ;  9/08/87  |    018.0 |  THE INCREMENT AND DECREMENT KEYS HAVE BEEN
92      ;           |          |  REVERSED TO COMPENSATE FOR PC BOARD R4.
93      ;-------------------------------------------------------------------------
94      ;
95      ;  9/03/87  |    017.0 |  THIS PROGRAM HAS BEEN MODIFIED TO RUN ON A 2 MHZ
96      ;           |          |  CLOCK.
97      ;           |          |  THE LOW BAT TIME HAS BEEN SET TO 15 MIN.
98      ;-------------------------------------------------------------------------
99      ;-------------------------------------------------------------------------
100     ;
101     ;  8/28/87  |    016.0 |  THE CLEAR DOSE FEATURE HAS BEEN DELETED
102     ;-------------------------------------------------------------------------
103     ;
```

```
104     ;  8/28/87  |    015.0 | THE HOLD ROUTINE HAS BEEN MODIFIED TO OCCUR
105     ;            |          | 2 1/2 MIN FROM LAST BUTTON PRESSED.
106     ;            |          | A WAIT STATEMENT HAS BEEN ADDED TO THE MAIN LOOP
107     ;            |          | AND OFF LOOP ROUTINES.
108     ;-------------------------------------------------------------------
109     ;  8/21/87  |    014.0 | THIS VERSION HAS BEEN MODIFIED TO ACCOMADATE
110     ;            |          | THE NEW ENCODED ROTARY SWITCH.
111     ;            |          | THE HOLD AND INCREMENT BUTTONS HAVE BEEN SWITCHED
112     ;            |          | TO SIMPLIFY THE RATE KNOB DECODE OPERATION.
113     ;-------------------------------------------------------------------
114     ;
115     ;  8/12/87  |    013.0 | THIS VERSION HAS BEEN REDUCED BY CONVERTING
116     ;            |          | THE RATE INCREMENT ROUTINES TO BINARY WITH
117     ;            |          | DECIMAL ADJUST ADDING.
118     ;-------------------------------------------------------------------
119     ;
120     ;  8/05/87  |    012.0 |  BLINK SUBROUTINE WAS MODIFIED SO THAT ONLY 3
121     ;            |          |  DIGITS ARE ACTIVE WHEN PUMP IS 224.
122     ;-------------------------------------------------------------------
123     ;
124     ;  7/30/87  |    011.0 |  MODIFIED SO THAT VOLUME AND DOSE CAN BE CLEARED
125     ;            |          |  WITH CLR V/D BUTTON WHILE PUMP IS RUNNING.
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126     ;         |          | THE DISPLAY HAS BEEN CHANGED TO EYE ERR IF
127     ;         |          | THE IR SENSOR IS BLOCKED DURING TEST SEQUENCE.
128     ;-------------------------------------------------------------------
129     ;
130     ;  7/25/87  |   010.0 |  MODIFY DOSE DEL ERROR, SO THAT PRESSING HOLD
131     ;         |          | BUTTON ONCE DISABLED ALARM AND MESSAGE. THIS
132     ;         |          | WILL ALLOW THE USER TO UPDATE DOSE OR VOLUME
133     ;         |          | WITH THE NEXT KEY STROKE.
134     ;-------------------------------------------------------------------
135     ;
136     ;  7/21/87  |   009.0 |  modified to display DP scroll when motor on
137     ;         |          |  in LOW BAT state.
138     ;-------------------------------------------------------------------
139     ;
140     ;  7/16/87  |   008.0 |  MODIFY HOLD BUTTON OPERATION FOR LO BAT STATE.
141     ;         |          |  WHEN HOLD PRESSED, ALARM STOPS AND MOTOR STOPS.
142     ;-------------------------------------------------------------------
143     ;
144     ;  7/13/87  |   007.0 |  ADD NO SET FEATURE.
145     ;         |          |  MODIFY VOLUME DISPLAY. ADD SHORTED MOTOR SENSOR
146     ;         |          |  DETECTION SOFTWARE. MODIFY 24 HR TIME ROUTINE
147     ;         |        |  TO CLEAR VOL DELIVERED, BUT NOT TO KILL POWER.
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148     ;-------------------------------------------------------------------
149     ; 7/10/87  |   006.0 |  FIX HIGH RATE ERROR BUG. MODIFIY LOW BAT TO
150     ;         |         |  CONTINUE TO RUN MOTOR WITH ALARM.
151     ;-------------------------------------------------------------------
152     ;
153     ; 7/08/87  |   005.0 |  TRY NEW INCREMENT METHOD FOR DOSE.
154     ;         |       |  SAVES APPROX. 40 BYTES. ADDED LOW BAT TIMER,
155     ;         |         |  AND DEAD BAT SIGNAL.
156     ;-------------------------------------------------------------------
157     ;
158     ; 7/07/87  |   004.0 |  324 RATE INCREMENT CHANGED TO 5 ML FOR RATES
159     ;         |         |  GREATER THEN 50.
160     ;-------------------------------------------------------------------
161     ;         |         |
162     ; 6/29/87  |   003.0 |  DOSE FEATURE IS ADDED. CURRENT SENSE SOFTWARE FOR
163     ;         |         |  SET DETECTION DELETED.
164     ;         |           |
165     ;-------------------------------------------------------------------
166     ; 6/25/87  |   002.0 |  RATE INITIALIZED TO 0 ON POWER UP AND
167     ;         |         |  TURN-ON. WRAP AROUND OF DISPLAY REMOVED.
168     ;
169     ;-------------------------------------------------------------------
```

```
170     ;           |          |
171     ;   6/01/87 |   001.0  | FIRST PUMP VERSION SEPARATED
172     ;           |          | FROM COMBO2.ASM
173     ;
174     $EJECT
```

```
175     ;=============================================================
176     ;
177     ;
178     ;            PORT ASSIGNMENTS                  A  ALL OUTPUTS
179     ;
180     ;
181     ; ------------------------------------------------------------
182     ;  7        6.       5        4        3        2        1        0
183     ; DP     /SEG g    /SEG f   /SEG e   /SEG d   /SEG c   /SEG b   /SEG a
184     ; ------------------------------------------------------------
185     ;
186     ;
187     ;                                      B  ALL OUTPUTS
188     ;
189     ;
190     ; ------------------------------------------------------------
191     ;  7        6        5        4        3        2        1        0
192     ; BUZZER  VOL CLR    5VA     POWER   /DIGIT 4 /DIGIT 3 /DIGIT 2 /DIGIT 1
193     ;        PMPID 1=224 1=ON    ON/OFF   (324)
194     ; ------------------------------------------------------------
195     ;
196     ;
```

```
197     ;                                                C  ALL INPUTS
198     ;
199     ;
200     ;  ------------------------------------------------------------------
201     ;   7        6        5        4        3        2        1        0
202     ; F1500/    AC/DC    /DROP    /LO BAT  /SET     /OFF     /B       /A
203     ; PUMP                                                    DOWN     UP
204     ;  ------------------------------------------------------------------
205     ;
206     ;
207     ;                                                D  0,1,2,3,4, INPUTS
208     ;                                                   5,6 OUTPUTS
209     ;
210     ;  ------------------------------------------------------------------
211     ;   7        6        5        4        3        2        1        0
212     ;  NC       IR-LED   NC       CLEAR    VOLUME   /HOLD    /DOSE    1/3
213     ;           ON/OFF                                                REV
214     ;  ------------------------------------------------------------------
215     ;
216
217
218     $EJECT
```

```
                219             DEFSEG ABSLSEG,ABSOLUTE
                220             SEG ABSLSEG
                221     ;
                222     ;
                223     ;*************** SET UP RAM/ROM AND PORT ADDRESSES **********************
                224     ;
=0040           225     USRRAM EQU    $40       ;STARTING ADDRESS OF USER RAM.
=1000           226     USRROM EQU    $1000     ;STARTING ADDRESS OF USER ROM.
=1C00           227     PMPTST EQU    $1C00     ;STARTING ADDRESS OF PUMP TEST SOFTWARE.
                228     ;
=0000           229     PORTA  EQU    $00       ;PORT A DATA.
=0001           230     PORTB  EQU    $01       ;PORT B DATA.
=0002           231     PORTC  EQU    $02       ;PORT C DATA.
=0003           232     PORTD  EQU    $03       ;PORT D DATA.
                233     ;
=0004           234     DDRA   EQU    $04       ;PORT A DATA DIRECTION REGISTER.
=0005           235     DDRB   EQU    $05       ;PORT B  "      "         "
=0006           236     DDRC   EQU    $06       ;PORT C  "      "         "
=0007           237     DDRD   EQU    $07       ;PORT D  "      "         "
=0008           238     TDR    EQU    $08       ;TIMER DATA REGISTER.
=0009           239     TCR    EQU    $09       ;TIMER CONTROL REGISTER.
=000A           240     MISC   EQU    $0A       ;MISCELLANEOUS REGISTER
```

```
                241     ;
                242     ;       ***************************************************************
                243     ;                       EQUATES
                244     ;       ***************************************************************
                245     ;
=101C           246     TABLE1      EQU   $101C
=1000           247     TABLE5      EQU   $1000
                248     ;
=0002           249     TIMEST      EQU   $02
                250     ;
=0003           251     T8MS  EQU   $03
=0003           252     T33MS EQU   $03
=000F           253     T1S   EQU   $0F         ;1/2 SEC TIME CONSTANT
=0002           254     T6M   EQU   $02         ;(02 + 1) =  03 x 2.0 = 6 MINUTES
=00EF           255     T142S EQU   $EF         ;(EF + 1) = 240 x 0.5 = 2 MINUTES
                256     ;
                257     ;
                258     ;**************** INTERRUPT/RESET VECTOR TABLE ***************************
                259     ;
=1FF4           260             ORG     $1FF4
                261     ;
1FF4 102D       262             DW      RESET   ;SERIAL INTERUPT TIMER 2
```

```
1FF6 1089          263             DW      TIMINP  ;TIMER INTERRUPT VECTOR (WAIT STATE)
1FF8 1089          264             DW      TIMINP  ;TIMER INTERRUPT VECTOR
1FFA 103E          265             DW      ONPOW   ;EXTERNAL INTERRUPT VECTOR
1FFC 103E          266             DW      ONPOW   ;SOFTWARE INTERRUPT VECTOR
1FFE 102D          267             DW      RESET   ;RESET VECTOR
                   268     ;
                   269     ;
                   270     $EJECT
```

```
                    271     ;
                    272     ;****************** DEFINE VARIABLES IN USER RAM AREA ********************
                    273     ;
                    274     ;
        =0040       275             ORG     USRRAM
                    276     ;
0040 00             277     TS      DB      0       ;READING OFF BRIDGE BEFORE RISE BEGINS (AMBIENT)
0041 00             278     T5      DB      0       ;READING FROM AMP  5  SECOND AFTER BRIDGE RISE.
0042 00             279     T10     DB      0       ;     "           10
0043 00             280     T15     DB      0       ;     "           15
0044 00             281     T20     DB      0       ;     "           20
0045 00             282     T25     DB      0       ;     "           25
                    283     ;
0046 00             284     ALGO    DB      0
                    285     ;
0047 00             286     TIMLO   DB      0       ;LOWER BYTE OF 5 MINUTE DOWN COUNTER.
0048 00             287     TIMHI   DB      0       ;UPPER  "     "    "     "     "
                    288     ;
0049 00             289     BATIM1  DB      0        ;15 MIN BATTERY TIMERS
004A 00             290     BATIM2  DB      0
                    291     ;
004B 00             292     HLDTM1  DB      0        ;HOLD TIME COUNTERS: 2 1/2 MIN
```

```
004C 00          293     HLDTM2 DB     0
                 294     ;
004D 00          295     SAMPL1 DB     0       ;STORAGE FOR THE LAST 5 A-TO-D READINGS.
004E 00          296     SAMPL2 DB     0       ;(SAMPL5 IS THE MOST RECENT).
004F 00          297     SAMPL3 DB     0
0050 00          298     SAMPL4 DB     0
                 299     ;
0051 00          300     DSPDG1 DB     0       ;7-SEGMENT DATA FOR LSD. (BIT 7 IS BACKPLANE CLOCK)
0052 00          301     DSPDG2 DB     0       ;"   "      "    "  DIG 2.
0053 00          302     DSPDG3 DB     0       ;"   "      "    "  DIG 3. (BIT 7 IS POWER CONTROL)
0054 00          303     DSPDG4 DB     0       ;"   "      "    "  MSD. (BITS 7-3 ARE A/D CONTROL)
                 304     ;
                 305     ;
                 306     ;
0055 00          307     DS1    DB     0          ;CONTAINS FIRST TWO DIGITS OF DOSE
0056 00          308     DS2    DB     0       ;CONTAINS LAST TWO DIGITS OF DOSE
                 309     ;
                 310     ;      DS1 AND DS2 ARE TRANSFERED TO SAMPL1-SAMPL4 BY BCDEXP
                 311     ;      ROUTINE.
                 312     ;
0057 00          313     DOSECT      DB     0          ;COUNTER FOR TIME IN DOSE MODE
                 314     ;
```

```
                315     ;    VS1 AND VS2 ARE TRANSFERRED TO SAMPL1-SAMPL4 BY BCDEXP
                316     ;
0058 00         317     DECML1      DB    0     ;FRACTION OF 1ML IN VOLUME
0059 00         318     VS1   DB      0       ;CONTAINS FIRST TO DIGITS OF VOLUME
005A 00         319     VS2   DB      0       ;CONTAINS LAST TO DIGITS OF VOLUME
                320     ;
005B 00         321     REG1   DB     0       ;TEMPORARY STORAGE
                322     ;
005C 00         323     REG2   DB     0       ;       "
                324     ;
005D 00         325     DRCNT1  DB      0     ;DROP COUNTERS
005E 00         326     DRCNT2      DB    0
                327
005F 00         328     REG3   DB     0       ;       "
0060 00         329     REG4   DB     0       ;       "
0061 00         330     REG5   DB     0       ;       "
                331     ;
                332     ;
                333     ;
                334     ;
```

```
0062 00          335    COUNT1 DB     0       ;GENERAL PURPOSE COUNTER REGISTER.
0063 00          336    COUNT2 DB     0       ;   "      "        "       "
0064 00          337    COUNT3 DB     0       ;   "      "        "       "
                 338    ;
                 339    ;************ REGISTERS AND VARIABLES USED DURING PREDICTION ************
                 340    ;
                 341    ;
0065 00          342    XH     DB     0       ;ARGUMENT STORAGE FOR 16-BIT MATH ROUTINES.
0066 00          343    XL     DB     0       ;                  "
0067 00          344    QH     DB     0       ;                  "
0068 00          345    QL     DB     0       ;                  "
0069 00          346    PH     DB     0       ;                  "
006A 00          347    PL     DB     0       ;                  "
                 348    ;
006B 00          349    TEMPA  DB     0
006C 00          350    TEMPX  DB     0
                 351    ;
006D 00          352    PSTAT1      DB    0     ;FIRST PUMP STATUS BYTE
                 353    ;                           0=HOLD    1=Unit on hold
                 354    ;                           1=MOTOR   1=Motor on
                 355    ;                           2=ON      1=Unit on
                 356    ;                           3=START   1=Unit in start mode
```

```
                    357     ;                       4=DISPLAY 1=Display on
                    358     ;                       5=CW      1=Clock wise rate change
                    359     ;                       6=CCW     1=Counter clock wise rate change
                    360     ;                       7=MODEL   1=324 0=224 Model
                    361     ;
                    362     ;
006E 00             363     PSTAT2      DB    0     ;SECOND PUMP STATUS BYTE
                    364     ;
     =006E          365     LOWBAT  EQU     PSTAT2      0=BATTERY 1=Low battery
     =006E          366     ACON    EQU     PSTAT2      1=AC      1=AC ON
     =006E          367     NDROP   EQU     PSTAT2      2=FLOW    1=Drop error
     =006E          368     HOLDER  EQU     PSTAT2      3=HOLD    1=Hold error
     =006E          369     NOSET   EQU     PSTAT2      4=SET     1=No set error
     =006E          370     ALRM    EQU     PSTAT2      5=ALARM   1=Audio alarm on
     =006E          371     VOLM    EQU     PSTAT2      6=VOLUME  1=Volume mode
     =006E          372     ERRON   EQU     PSTAT2      7=ERROR   1=Error mode
                    373     ;
006F 00             374     TSTERR      DB    0     ;B0 IS TEST ERROR FLAG
                    375                           ; SET IF EYES BLOCKED DURING TEST
                    376     ;
0070 00             377     DOSER   DB      0       ;DOSE DELIVIRED FLAG BO=1: DOSE DEL
0071 00             378     DFLAG DB    0     ;DOSE MODE FLAG
```

```
                379     ;                   B0= DOSE    1=DOSE MODE ON
                380     ;                   B1= DTEST   1=DOSE BUTTON PRESSED
                381     ;                               LAST CYCLE, USED FOR
                382     ;                               DEBOUNCE.
                383     ;                   B2= ZERO    1=DISPLAY ZERO
                384     ;
0072 00         385     LTEST       DB  0       ;MAGNET LOW COUNTER, USED TO CHECK IF SENSOR
                386                             ;IS STUCK LOW. INCREMENTED AS LONG REV SIGNAL
                387                             ;IS LOW. CLEARED WHEN SIGNAL GOES HIGH.
0073 00         388     HTEST DB    0       ;B0 - TEST FLAG FOR HOLD DEBOUNCE
                389     ;                   ;B1 - TEST FLAG FOR CLR VOL DEBOUNCE
0074 00         390     ZEROST      DB  0       ;ZERO STATUS FLAG
                391                             ; B5 = 1 : DISPLAY IS ZERO
                392                             ; B6 = 1 : MSD IS ZERO
                393                             ; B7 = 1 : MSD-1 IS ZERO
                394     ;
0075 00         395     VFLAG DB    0       ;VOLUME DISPLAY TEST FLAG. SET WHEN 'VOL'
                396                             ;IS DISPLAYED.
0076 00         397     CWF   DB    0       ;CLOCKWISE FLAG
0077 00         398     CCWF  DB    0       ;COUNTER CLOCKWISE FLAG
0078 00         399     SPEED1      DB  0       ;ROLL UP/DOWN SPEED
0079 00         400     VOLTIM      DB  0       ;VOLUME MODE ON TIMER
```

```
007A 00          401    THIRD1   DB   0    ;1/3 REV COUNTER
007B 00          402    THIRDR   DB   0    ;1/3 REV COUNTER
007C 00          403    OUTSPD   DB   0    ;SCROLLING SPEED COUNTER
007D 00          404    MOTIM1   DB   0    ;FIRST MOTOR TIME COUNTER
007E 00          405    MOTIM2   DB   0    ;SECOND MOTOR TIME COUNTER
007F 00          406    ERRCNT   DB   0    ;COUNTING FOR TWO ERROR MODES
0080 00          407    DSPTST   DB   0    ;TEST FLAG
0081 00          408    COUNT4   DB   0    ;DROP COUNTER
0082 00          409    LSTRAT   DB   0    ;LAST RATE USED FOR ENCODED RATE KNOB
                 410    ;
0083 00          411    CKBEP DB   0       ;CHECK BEEP FLAG USED IN CKCLR
0084 00          412    CKTIM DB   0       ;USED IN CKCLR TO TIME BEEP
                 413    ;
                 414
                 415
    =1000        416         ORG   USRROM
                 417    ;
                 418    ;
```

```
                    419     ;   ************************************************************
                    420     ;                   CONSTANTS IN ROM
                    421     ;   ************************************************************
                    422     ;
1000 F8 9C FF       423     LO    DB    $F8,$9C,$FF       ;DISPLAY LO ON LEDS
1003 98 81 B8       424     BATT  DB    $98,$81,$B8       ;DISPLAY BAT ON LEDS
1006 B1 F8 C0       425     FLO   DB    $B1,$F8,$C0       ;DISPLAY FLO ON LEDS
1009 B0 BD BD       426     ERR   DB    $B0,$BD,$BD       ;DISPLAY ERR ON LEDS
100C 9D 9C FF       427     NO    DB    $9D,$9C,$FF       ;DISPLAY NO ON LEDS
100F 92 B0 B8       428     SET   DB    $92,$B0,$B8       ;DISPLAY SET ON LEDS
1012 89 F8 8C       429     HLD   DB    $89,$F8,$8C       ;DISPLAY HLD ON LEDS


1015 8C 9C 92 B0    430     DOSE  DB    $8C,$9C,$92,$B0         ;DISPLAY DOSE ON LEDS
1019 8C B0 F8       431     DEL         DB    $8C,$B0,$F8       ;DISPLAY OUT ON LEDS
101C 92 8A 92       432     SYS   DB    $92,$8A,$92       ;DISPLAY SYS ON LEDS
101F C0 CF A4 86    433     DIGITS      DB    $C0,$CF,$A4,$86,
1023 8B                     $8B   ;DISPLAY NUMBERS 0-9 ON LED
1024 92 90 C7 80    434           DB    $92,$90,$C7,$80,
1028 83                     $83
                    435     ;
1029 F7 FB FD FE    436     DNUM  DB    $F7,$FB,$FD,$FE         ;DIGIT OUTPUT
```

```
;
;****************************************************************************
;
$EJECT
```

```
                        441     ;
                        442     ;-------------------------------------------------------------------
                        443     ;                   START FROM RESET
                        444     ;-------------------------------------------------------------------
                        445     ;
                        446     ;              (THIS IS THE POWER-ON RESET ENTRY POINT)
                        447     ;
                        448     ;*******************************************************************
                        449     ;
                        450     ;
102D AE 40              451     RESET   LDX     #$40    ;FIRST, CLEAR RAM.
102F 4F                 452             CLRA
1030 F7                 453     CLEAR   STA     ,X
1031 5C                 454             INCX
1032 A3 FF              455             CPX     #$FF
1034 26 FA              456             BNE     CLEAR
                        457
                        458     ;
                        459     ;               Set up the ports
                        460     ;
1036 CD 1106            461             JSR   TIMEON            ;GO START TIMER COUNTER
1039 1A 0A              462             BSET  5,MISC            ;SET INT SENSE FOR EDGE AND LEVEL
```

```
                    463     ;
                    464     ;               Wait for timer inturrupt
                    465     ;
103B 8F             466     LOOPW   WAIT
103C 20 FD          467             BRA   LOOPW
                    468     ;
                    469     $EJECT
```

```
                    470     ;
                    471     ;
                    472     ;       ---------------------------------------------------------
                    473     ;               EXTERNAL INTURRUPT HANDLER
                    474     ;       ---------------------------------------------------------
                    475     ;
                    476     ;
                    477     ;
103E 1B 0A          478     ONPOW BCLR  5,MISC          ;RETURN INT SENSE TO EDGE LEVEL
1040 0E 6E 45       479           BRSET    7,ERRON,NOON     ;IF IN ERROR MODE DONT DO
1043 04 6D 42       480         BRSET 2,PSTAT1,NOON    ;DONT DO IF ON
                    481     ;
1046 A6 19          482         LDA   #$19       ;INITIALIZE PUMP STAT REGISTOR
1048 B7 6D          483         STA   PSTAT1
                    484     ;
                    485     ;   CHECK PORTB(6) FOR PUMP ID
                    486     ;
104A 1E 6D          487         BSET  7,PSTAT1   ;PRESET ID FLAG FOR 324
104C A6 FF          488         LDA   #$FF       ;PRELOAD ACCA TO SET PORTB ALL OUTPUT
104E 0D 01 04       489         BRCLR 6,PORTB,CONON    ;IF PORTB(6)=0, PMP IS 324 SO CONTINUE
1051 1F 6D          490         BCLR  7,PSTAT1   ;ELSE, PMP IS 224 SO CLEAR ID FLAG
1053 A6 BF          491         LDA   #$BF       ; AND SET ACCA TO MAKE PORTB(6) INPUT
```

```
                492     ;
1055 B7 05      493     CONON STA   DDRB        ;CONFIGURE PORTB TO BF OR FF
1057 A6 FF      494           LDA   #$FF
1059 B7 04      495           STA   DDRA        ;CONFIGURE PORTA TO ALL OUTPUTS
105B B7 00      496           STA   PORTA       ;MAKE PORTA ALL 1'S
105D A6 1F      497             LDA #$1F              ;
105F B7 01      498           STA   PORTB       ; PORTB=0001 1111
1061 A6 60      499           LDA   #$60            ;MAKE PORT D 0-4 INPUTS 5,6 OUTPUTS
1063 B7 07      500           STA   DDRD
1065 4F         501           CLRA
1066 B7 03      502           STA   PORTD
1068 B7 06      503           STA   DDRC
                504     ;
                505
                506     ;               Initialize display pointers
                507     ;
                508                             ;SET UP INITIAL DISPLAY
                509                           ;POINTERS SO DISPLAY
                510                                 ;READS 0
                511                           ;WHEN THE DISPLAY IS
                512                           ;ACTIVATED
                513     ;
```

```
106A 3F 79      514          CLR   VOLTIM          ;CLEAR THE VOLUME DISPLAY TIMER
                515     ;
106C 5F         516          CLRX                  ;INITIALIZE DOSE
106D 4F         517          CLRA                  ;AND RATE
106E E7 51      518     CLEAR1    STA   DSPDG1,X    ;DISPLAY
1070 5C         519          INCX                  ;TO READ ZERO
1071 A3 07      520          CPX   #07             ;
1073 26 F9      521          BNE   CLEAR1          ;
1075 1A 74      522          BSET  5,ZEROST        ;SET DISPLAY ZERO FLAG
1077 14 71      523          BSET  2,DFLAG         ;SET DOSE ZERO FLAG
                524     ;
1079 1D 6E      525          BCLR  6,VOLM          ;CLEAR THE VOLUME FLAG
107B 10 80      526          BSET  0,DSPTST        ;SET TEST FLAG
107D CD 1756    527          JSR    UPDATE         ;GO SET DISPLAY TO READ 125
1080 14 6D      528          BSET  2,PSTAT1        ;UNIT ON
                529     ;
                530     ;         INITIALIZE RATE KNOB LOCATION
                531     ;
1082 B6 02      532          LDA   PORTC           ;GET PORTC
1084 A4 03      533          AND   #$03            ;MASK 2 LOWER BITS
1086 B7 82      534          STA   LSTRAT          ;STORE IN LAST RATE LOCATION
                535     ;
```

```
1088 80        NOON  RTI
               ;
               ;
               $EJECT
```

```
                    540     ;
                    541     ;    ---------------------------------------------------------
                    542     ;          TIMER INTERRUPT ROUTINE
                    543     ;    ---------------------------------------------------------
                    544     ;
                    545     ;          This routine is called every-
                    546     ;
                    547     ;  2.00 ms it services the LED mux.
                    548     ;  8.00 ms it calls rpm, motor on, rate, hold, and off.
                    549     ;  32.00 ms it checks  drop status and set.
                    550     ;  .5000 s it checks for low battery, updates charge status and display on/off
                    551     ;  142. s it checks charge time to control battery charge rate.
                    552     ;
                    553     ;       *************** 2  MS CHECK LOOP *********************************
                    554     ;
1089 A6 F9          555     TIMINP      LDA   #$F9
108B B7 08          556           STA   TDR
108D 1F 09          557             BCLR    7,TCR           ;RESET THE TIMER
                    558
                    559     ;
108F CD 110C        560           JSR   WATCHD          ;GO OUTPUT PULSE TO HOLD OFF AUTO RESET
1092 CD 1115        561           JSR   LED         ;GO MULTIPLEX THE LEDS
```

```
1095 CD 12DA      562            JSR   INRATE1          ;GO UPDATE RATE FOR 224
1098 CD 1185      563            JSR   DROPCK           ;GO CHECK FOR DROP
                  564      ;
109B B6 40        565            LDA   TS         ;TEST IF TIME TO DO NEXT TESTS
109D 3C 40        566            INC   TS
109F A1 03        567            CMP   #T8MS
10A1 27 01        568            BEQ   TIME2
10A3 80           569            RTI
                  570      ;
                  571      ;       *************** 8 MS LOOP ************************************
                  572      ;
10A4 3F 40        573      TIME2 CLR   TS
                  574      ;
10A6 CD 11CF      575            JSR   RPMCK       ;GO CHECK MOTOR FOR ONE RPM
10A9 CD 1290      576            JSR   MOTCK       ;GO CHECK MOTOR TIME TO TURN ON
10AC CD 12BD      577            JSR   SETCK       ;GO CHECK FOR SET CURRENT
10AF CD 140E      578            JSR   OFFCK       ;GO SEE IF OFF PUSHED
                  579      ;
10B2 B6 41        580            LDA   T5          ;GET STATUS OF SECOND TIMER
10B4 3C 41        581            INC   T5          ;INCREMENT FOR NEXT TIME
10B6 A1 03        582            CMP   #T33MS           ;DOES IT EQUAL 32 MS
10B8 27 01        583            BEQ   TIME3       ;YES SO GO TEST
```

```
10BA 80          584          RTI              ;RETURN TO PROGRAM
                 585     ;
                 586     ;       ************** 33 MSEC CHECK LOOP *******************************
                 587     ;
10BB 3F 41       588     TIME3 CLR   T5         ;CLEAR T5 FOR NEXT TIME THRU
                 589     ;
10BD CD 1458     590          JSR   TESTD       ;DO TEST DISPLAY
10C0 CD 14EC     591          JSR   HOLDCK           ;GO TEST IF HOLD PRESSED
10C3 CD 15A9     592          JSR   DOSECK           ;GO CHECK DOSE BUTTON
10C6 CD 15EE     593          JSR   VOLDIS           ;DISPLAY VOLUME CHECK MODEL 324
10C9 CD 1640     594          JSR   CKCLR       ;GO CHECK VOLUME CLEAR
10CC CD 1687     595          JSR   INRATE2          ;INPUT ROUTINE FOR MODEL 324
                 596     ;
10CF B6 42       597          LDA   T10         ;GET TIMER3 STATUS
10D1 3C 42       598          INC   T10         ;INCREMENT FOR NEXT TIME
10D3 A1 0F       599          CMP   #T1S        ;DOES IT EQUAL 1S
10D5 27 01       600          BEQ   TIME4       ;YES SO GO TIME4
10D7 80          601          RTI               ;RETURN TO PROGRAM
                 602     ;
                 603     ;       **************  1/2 SEC BAT CHECK ****************************
                 604     ;
10D8 3F 42       605     TIME4 CLR   T10         ;RESET TIMER3 FOR NEXT TIME
```

```
                    606     ;
10DA CD 17DD        607             JSR   ACDC        ;GO TEST AC OR DC
10DD CD 17E6        608             JSR   BATCK       ;GO DO BATTERY CHECK
10E0 CD 1836        609             JSR   DBATCK            ;GO CHECK FOR DEAD BATTERY
10E3 CD 184E        610             JSR     ALARM           ;GO TEST ALARM
10E6 CD 1860        611             JSR   BLINK       ;GO BLINK DISPLAY
10E9 CD 1909        612             JSR   HLDER       ;go test if on hold 142sec then error
                    613     ;
10EC B6 43          614     NO5     LDA   T15         ;GET TIMER4 STATUS
10EE 3C 43          615             INC   T15         ;ADD ONE FOR NEXT TIME
10F0 A1 EF          616             CMP   #T142S            ;DOES IT EQUAL 142 SEC
10F2 27 01          617             BEQ   TIME5       ;YES SO GO TIME 5
10F4 80             618               RTI             ;RETURN TO PROGRAM
                    619     ;
                    620     ;       ********************** 142 SEC LOOP ***************************
                    621     ;
10F5 3F 43          622     TIME5 CLR   T15           ;CLEAR FOR NEXT TIME
                    623     ;
                    624     ;
10F7 B6 44          625             LDA   T20
10F9 3C 44          626             INC   T20
10FB A1 02          627             CMP   #T6M
```

```
10FD 27 01          628          BEQ   TIME6
10FF 80             629          RTI
                    630     ;
                    631     ;      ******************** 2415 SEC LOOP *************************
                    632     ;
1100 3F 44          633     TIME6 CLR   T20
                    634     ;
1102 CD 192E        635          JSR   TIM24          ;go test if off 24 hrs then kill power
                    636     ;
1105 80             637          RTI
                    638     ;
                    639     ;
                    640     $EJECT
```

```
                    641     ;=============================================================
                    642     ;                          SUBROUTINES
                    643     ;=============================================================
                    644     ;
                    645     ;
                    646     ;
                    647     ;               INITIALIZE COUNTER TIMER
                    648     ;-------------------------------------------------------------
                    649     ;
                    650     ;
                    651     ;
1106 A6 02          652     TIMEON      LDA   #TIMEST          ;SET COUNTER TO 4
1108 B7 09          653           STA   TCR          ;ENABLE TIMER INT
110A 9A             654           CLI                ;ENABLE INTERRUPTS
110B 81             655           RTS                      ;RETURN;
                    656     ;
                    657     ;
                    658     ;
                    659     ;               WATCH DOG TIMER
                    660     ;-------------------------------------------------------------
                    661     ;                Output clock to hold off reset
                    662     ;
```

```
110C 0B 03 03      663     WATCHD      BRCLR 5,PORTD,SETTR     ;IF CLOCK LOW MAKE HIGH
110F 1B 03         664             BCLR  5,PORTD
1111 81            665             RTS
                   666     ;
1112 1A 03         667     SETTR BSET  5,PORTD
1114 81            668             RTS
                   669     ;
                   670     $EJECT
```

```
                671     ;
                672     ;
                673     ;                LED MUX ROUTINE
                674     ;
                675     ;       This routine is called every 4 ms
                676     ;       It handles 0 supression and outputs 7 seg data
                677     ;       VARIABLES USED: COUNT3=This is the digit number and is changed every
                678     ;                               time this routine is called.
                679     ;                       SAMPLE1=location of Current value of digit 1.
                680     ;                               add count3 and use as pointer.
                681     ;                       7,pstat2 (error)=test if in error mode for blinking.
                682     ;                       4,pstat1 (display)=test if display blanked (blinking
                683     ;                               mode).
                684     ;                       ZEROST=bit 6 set=zero in msd
                685     ;                              bit 7 set=zero in next digit
                686     ;
                687     ;
                688     ;-----------------------------------------------------------------------
                689     ;
1115 05 6D 36   690     LED     BRCLR   2,PSTAT1,NOD4   ;IF UNIT OFF DONT DO MUX
1118 A6 0F      691             LDA     #$0F            ;Turn all digits off
111A BA 01      692             ORA     PORTB
```

```
111C B7 01        693            STA   PORTB
111E BE 64        694            LDX     COUNT3          ;GET CURRENT DIGIT NO.
1120 A3 03        695            CPX   #$03          ;HAVE WE DONE 4
1122 26 04        696            BNE   GO            ;IF NOT GO ON
1124 3F 64        697            CLR   COUNT3            ;IF SO RESET ALL VARIABLES
1126 20 02        698            BRA   GO2
                  699      ;
1128 3C 64        700      GO    INC     COUNT3
                  701      ;
112A 0C 6E 0E     702      GO2   BRSET 6,VOIM,NOTZRO     ;IF IN VOL NO ZERO TEST
112D 00 71 0B     703            BRSET       0,DFLAG,NOTZRO    ;IF IN DOSE NO ZERO TEST
1130 A3 03        704            CPX   #$03          ;IF DIGIT 1 DONT TEST FOR 0
1132 27 07        705            BEQ   NOTZRO
1134 CD 1175      706            JSR   TEST0         ;GO TEST
1137 24 02        707            BCC   NOTZRO            ;IF NO CARRY IT CANT BE 0
1139 20 14        708            BRA   ZERO
                  709      ;
                  710      ;
113B E6 4D        711      NOTZRO      LDA   SAMPL1,X
113D 0E 6E 05     712           BRSET 7,ERRON,OUT1       ;IF error mode dont blank
1140 08 6D 02     713           BRSET 4,PSTAT1,OUT1      ;if display on flag set dont blank
1143 4F           714           CLRA                      ;blank display if display flag is low
```

```
1144 43          715          COMA                    ;SET PORTA=FF ALL OFF
                 716     ;
1145 B7 00       717     OUT1 STA   PORTA
1147 D6 1029     718          LDA   DNUM,X            ;GET DIGIT TO OUTPUT
114A B4 01       719          AND   PORTB             ;ENABLE
114C B7 01       720          STA   PORTB
114E 81          721     NOD4 RTS
                 722     ;
                 723     ;
114F A3 00       724     ZERO CPX   #$00         ;IS THIS FIRST TIME THROUGH (MSD)
1151 27 17       725          BEQ   ZERO1             ;IF SO BLANK AND SET FLAG IF ZERO
1153 A3 01       726          CPX   #$01              ;IS THIS SECOND TIME THRU
1155 27 17       727          BEQ   ZERO2             ;IF SO CHECK FIRST FLAG
1157 0D 74 E1    728          BRCLR 6,ZEROST,NOTZRO ;ON THIRD TIME CHECK FIRST TWO
115A 0F 74 DE    729          BRCLR 7,ZEROST,NOTZRO ;IF EITHER NOT SET DONT BLANK
                 730     ;
115D E6 4D       731     ZEROT LDA   SAMPL1,X    ;GET DIGIT DATA
115F 49          732          ROLA                    ;CHECK IF DP ON
1160 24 04       733          BCC   ZERODP            ;IF SO LEAVE ON
1162 A6 FF       734          LDA   #$FF              ;IF NOT BLANK
1164 20 DF       735          BRA   OUT1              ;GO OUTPUT IT
1166 A6 7F       736     ZERODP       LDA   #$7F             ;LEAVE DP ON
```

```
1168 20 DB          737          BRA   OUT1
                    738     ;
                    739     ;
116A 1C 74          740     ZERO1 BSET  6,ZEROST    ;SET ZERO FLAG
116C 20 EF          741           BRA   ZEROT           ;OUTPUT BLANK
116E 0D 74 CA       742     ZERO2 BRCLR 6,ZEROST,NOTZRO ;CHECK FIRST DIGIT FLAG
1171 1E 74          743           BSET  7,ZEROST        ;IF SET THEN BLANK 2ND DIGIT
1173 20 E8          744           BRA   ZEROT
                    745     ;
1175 E6 4D          746     TEST0 LDA   SAMPL1,X    ;test if digit is 0
1177 98             747           CLC
1178 49             748           ROLA
1179 A1 80          749           CMP   #$80
117B 27 04          750           BEQ   SETCAR
117D 98             751           CLC             ;clr carry if not zero
117E E6 4D          752           LDA   SAMPL1,X
1180 81             753           RTS
1181 99             754     SETCAR      SEC                 ;set carry if it is
1182 E6 4D          755           LDA   SAMPL1,X
1184 81             756           RTS
                    757     ;
                    758     $EJECT
```

```
                    759     ;
                    760     ;                   DROP CHECK
                    761     ;
                    762     ;              This routine is called every 8ms
                    763     ;              After a delay of .4 sec to clear all transients,
                    764     ;            it turns on the IR source and looks at the photo transistor.
                    765     ;                 If the line is low a drop is there the counter is cleared.
                    766     ;           If there is no drop the counter is incremented and if it reaches
                    767     ;           a count of 95 or 95 X .008=.76 sec then the second counter is incremented
                    768     ;           This counter is tested in the RPM routine if it gets to 2 or 1.76s then
                    769     ;           it will alarm.
                    770     ;
                    771     ;-----------------------------------------------------------------
                    772     ;           Conditions
                    773     ;
1185 05 6D 43       774     DROPCK      BRCLR 2,PSTAT1,NODRP    ;DONT DO IF UNIT OFF
1188 00 6D 40       775           BRSET 0,PSTAT1,NODRP    ;DONT DO IF PUMP NOT IN RUN MODE
                    776     ;
                    777     ;     CHECK RATE
                    778
118B B6 53          779           LDA   DSPDG3            ;IF RATE < 100, CHECK FOR DROPS
118D A1 01          780           CMP   #$01
```

```
118F 25 03          781             BLO   DELCK
1191 03 6D 37       782             BRCLR 1,PSTAT1,NODRP   ELSE, CHECK DROPS WHEN MOTOR ON ONLY
                    783     ;
                    784     ;       DELAY CHECK
                    785     ;
1194 B6 5B          786     DELCK LDA   REG1        ;CHECK REG1
1196 A1 7C          787           CMP   #124        ;IF 0.248 SEC ELAPSED SINCE MOTOR ON
1198 27 04          788           BEQ   DROP1       ;DO DROP TEST AND SKIP INCREMENT.
119A 4C             789           INCA              ;ELSE,
119B B7 5B          790           STA   REG1        ;INCREMENT AND RETURN.
119D 81             791           RTS
                    792     ;
                    793     ;         Test for drop
                    794     ;
119E 1C 03          795     DROP1 BSET    6,PORTD         ;TURN IR SOURCE ON
11A0 9D             796           NOP               ;ADD SOME DELAY TO ALLOW SETTLING
11A1 9D             797           NOP
11A2 9D             798           NOP
11A3 9D             799           NOP
                    800     ;
11A4 0A 02 1C       801             BRSET   5,PORTC,CLERK       ;CHECK FOR LOW (DROP)
11A7 1D 03          802           BCLR  6,PORTD           ;TURN OFF IR SENSOR
```

```
11A9 10 81          803          BSET  0,COUNT4    ;WE HAVE DROP SO SET FLAG
                    804     ;
11AB 3C 5D          805          INC   DRCNT1          ;INCREMENT DROP COUNTERS
11AD 26 02          806          BNE   CONDRP
11AF 3C 5E          807          INC   DRCNT2
11B1 B6 5E          808     CONDRP    LDA   DRCNT2          ;CHECK IF DROP CNT = 0.76 SEC
11B3 A1 01          809          CMP   #$01
11B5 25 14          810          BLO   NODRP       ;IF DRCNT2 < 1 END TEST
11B7 B6 5D          811          LDA   DRCNT1          ;ELSE CHECK DROP CNT 1
11B9 A1 7C          812          CMP   #$7C
11BB 27 02          813          BEQ   NEXTBY          ;IF DRCNT1 >= 7C, INCREMENT REG3
11BD 20 0C          814          BRA   NODRP       ;ELSE, EXIT DROPCK
                    815     ;
11BF 3C 5F          816     NEXTBY    INC   REG3
11C1 20 08          817          BRA   NODRP       ;REG3 IS TESTED IN THE RPM ROUTINE
                    818     ;                      ; IF 2 IT ERRORS
                    819     ;
                    820     ;        No drop
                    821     ;
11C3 1D 03          822     CLERK BCLR  6,PORTD
11C5 3F 5D          823          CLR   DRCNT1          ;CLEAR THE COUNTERS FOR BLOCKED EYES
11C7 3F 5E          824          CLR   DRCNT2
```

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```
11C9 3F 5F         CLR     REG3
11CB 81      NODRP RTS
             ;
             ;
             $EJECT
```

```
                    830     ;
                    831     ;
                    832     ;
                    833     ;                       RPM  CHECK
                    834     ;-------------------------------------------------------------------
                    835     ;    This routine samples the hall effect line. At rates over 95 it stops
                    836     ;     the motor every 3 magnets or one rev. At rates under 100 it stops
                    837     ;     every magnet 1/3 rev.
11CC CC 1230        838     RPM3  JMP   RPM1
                    839     ;
                    840     ;        Conditions
                    841     ;
11CF 05 6D F9       842     RPMCK BRCLR 2,PSTAT1,NODRP    ;DONT DO IF UNIT OFF
11D2 03 6D F6       843           BRCLR 1,PSTAT1,NODRP    ;DON'T DO IF MOTOR IS OFF
                    844     ;
                    845     ;         Delay until circuit settles
                    846     ;
11D5 B6 7E          847           LDA   MOTIM2            ;DON'T DO IF MOTOR NOT RUN ENOUGH
11D7 26 06          848           BNE   RPM2        ;IF 2ND BYTE >0 THEN DO TEST
11D9 B6 7D          849           LDA   MOTIM1            ;IF=0M THEN TEST 1ST BYTE FOR>$32
11DB A1 56          850           CMP   #86               ;
11DD 25 EC          851           BLO   NODRP             ;IF <THEN 86*.00816=.7017 SEC THEN DONT DO
```

```
                852     ;
                853     ;       Test magnet
                854     ;
11DF 00 03 EA   855     RPM2  BRSET 0,PORTD,RPM3    ;IF LINE HIGH THERE IS NO MAGNET
11E2 3F 7F      856           CLR   ERRCNT
11E4 3C 72      857           INC   LTEST       ;UPDATE MAG LOW COUNTER
11E6 B6 72      858           LDA   LTEST
11E8 A1 FF      859           CMP   #255              ;IF MAG SENSED FOR 2 CONS. SEC
11EA 27 62      860           BEQ   TIMERR            ;THEN MAGNET OR ROTOR ERROR.
11EC A1 01      861           CMP   #$01        ;IF LTEST > 1,
11EE 22 3F      862           BHI   NORPM       ;SAME PULSE DETECTED SO DON'T UPDATE
                863     ;
                864     ;---------- If this is model 324 add .376 to volume for every rev ------
                865     ;
11F0 0F 6D 12   866           BRCLR 7,PSTAT1,OFMOT1  ;IF 224 DONT ADD
                867     ;
11F3 CD 126D    868           JSR   CALCV       ;ELSE, CALCULATE VOLUME
                869
                870     ;
                871     ;
11F6 0D 6E 06   872     XYZV  BRCLR 6,VOLM,OFMOT      ;IF NOT IN VOLUME MODE OR
11F9 00 75 03   873           BRSET 0,VFLAG,OFMOT     ;VOL TEST DISPLAY ENABLED
```

```
11FC CD 1634    874          JSR   VSEXP       ;GO UPDATE VOLUME NUMBERS
                875     ;
                876     ;-----------------------------------------------------------------
                877     ;
                878     ;
                879     ;       Test 1/3 OR 1 REV  AND Turn off the motor
                880     ;
11FF B6 55      881     OFMOT LDA   DS1             ;IF DOSE!=0, CHECK DOSE
1201 BA 56      882           ORA   DS2


1203 26 36      883           BNE   CMPDOS
                884     ;
1205 3F 5B      885     OFMOT1      CLR   REG1
1207 3C 61      886           INC   REG5        ;CHECK IF THIS IS START UP
1209 B6 61      887           LDA   REG5        ;IF SO IGNORE THE FIRST MAGNET
120B A1 02      888           CMP   #$02        ;AS IT COULD BE LESS THEN 1/3
120D 25 20      889           BLO   NORPM       ;IT IS SO JUMP OVER SET CHECK
                890     ;
120F 3A 61      891           DEC   REG5        ;ITS NOT START SO KEEP FROM OVERFLOW
1211 3C 7A      892           INC   THIRD1
1213 B6 7A      893           LDA   THIRD1
```

```
1215 A1 03          894             CMP   #$03
1217 26 0A          895             BNE   OFF90
1219 3F 7A          896             CLR   THIRD1
                    897     ;
                    898     ;         If drop flag not set then error
                    899     ;
121B 01 81 43       900             BRCLR 0,COUNT4,DROPER
121E 02 5F 40       901             BRSET 1,REG3,DROPER          ;EYES BLOCKED FOR 1 REV
                    902     ;
1221 3F 81          903             CLR   COUNT4
1223 B6 53          904     OFF90   LDA   DSPDG3            ;CHECK IF >95 RATE
1225 26 31          905             BNE   STP3        ;IF RATE >100 THEN STOP EVERY 3 SENSORS
1227 20 02          906             BRA   OFFM1
                    907     ;
1229 10 6D          908     OFFM    BSET  0,PSTAT1    ;SET HOLD FLAG TO DISABLE MOTCK
122B 13 6D          909     OFFM1   BCLR  1,PSTAT1    ;MOTOR OFF PSTAT
122D 1B 01          910             BCLR  5,PORTB           ;MOTOR OFF
122F 81             911     NORPM   RTS
                    912     ;
                    913     ;
                    914     ;
                    915     ;
```

```
                        916     ;
                        917     ;       Reset pulse status
                        918     ;
1230 3F 72              919     RPM1  CLR     LTEST           ;CLEAR MAG LOW COUNTER
1232 3C 7F              920           INC     ERRCNT
1234 B6 7F              921           LDA     ERRCNT
1236 A1 FF              922           CMP     #255        ;IF NO MAGNET IN 255X.008=2.04 SEC THEN ERR
1238 27 14              923           BEQ     TIMERR
123A 81                 924           RTS
                        925     ;
                        926     ;
123B CD 1951            927     CMPDOS  JSR     CPVTOD              ;CALL COMPARE VOL TO DOSE
123E A3 FF              928           CPX     #$FF                  ;X IS FF IF VOL >= DOSE
1240 26 C3              929           BNE     OFMOT1                ;IF X NOT FF, CONTINUE
                        930     ;                               ;ELSE DOSERR
                        931     ;
1242 10 70              932     DOSERR      BSET  0,DOSER
1244 B6 6E              933           LDA     PSTAT2
1246 AA A0              934           ORA     #$A0
1248 A4 BD              935           AND     #$BD
```

```
124A B7 6E          936             STA   PSTAT2
124C 20 DB          937             BRA   OFFM
                    938     ;
                    939     ;
124E 1E 6E          940     TIMERR      BSET  7,ERRON          ;ENABLE ERROR FLAG
1250 1A 6E          941             BSET  5,ALRM          ;ENABLE ALARM
1252 3F 7F          942             CLR   ERRCNT
1254 CD 1229        943             JSR   OFFM
1257 81             944             RTS
                    945     ;
                    946     ;       Count every 3 magnet hits
                    947     ;
1258 3C 7B          948     STP3    INC   THIRDR          ;BUMP THIRD OF A REV COUNTER;
125A B6 7B          949             LDA   THIRDR
125C A1 03          950             CMP   #$03        ;IF THIRD ONE THEN STOP
125E 24 CB          951             BHS   OFFM1       ;DONT SET HOLD FLAG
1260 81             952             RTS
                    953     ;
                    954     ;
                    955     ;       No drop error
                    956     ;
1261 14 6E          957     DROPER      BSET  2,NDROP         ;SET FLOW ERROR FLAG
```

```
1263 1E 6E      958           BSET  7,ERRON          ;ENABLE DISPLAY ERROR MODE
1265 1A 6E      959           BSET  5,ALRM           ;ENABLE ALARM ERROR
1267 1D 6E      960           BCLR  6,VOLM             ;GET OUT OF VOLUME MODE
1269 11 71      961           BCLR  0,DFLAG          ;CLEAR DOSE MODE FLAG
126B 20 BC      962           BRA   OFFM
                963      ;
                964      ;              .125 ml/ 1/3 rev 8*.125=1
                965      ;
126D 3C 58      966      CALCV INC    DECML1           ;INCREMENT DECML COUNTER
126F B6 58      967           LDA   DECML1
1271 A1 08      968           CMP   #$08         ;IF DECML=8, TIME TO INCREMENT VS1, VS2
1273 26 1A      969           BNE   ENDCALC           ;ELSE, ENDCALC
                970      ;
1275 3F 58      971           CLR   DECML1           ;CLEAR DECML COUNTER
                972      ;
1277 A6 99      973           LDA   #$99         ;CHECK FOR FULL COUNTER
1279 B1 59      974           CMP   VS1
127B 26 04      975           BNE   CONCAL            ;IF VS1 != 99, CONTINUE CALCULATION
127D B1 5A      976           CMP   VS2          ;ELSE, CHECK VS2
127F 27 0E      977           BEQ   ENDCALC           ;IF VS1 & VS2 = 99, END CALCULATION
                978      ;
1281 B6 59      979      CONCAL     LDA   VS1          ;INCREMENT VS1
```

```
1283 AB 01      980          ADD   #$01
1285 8D         981          DAA             ;DECIMAL ADJUST RESULT
1286 B7 59      982          STA   VS1             ;STORE VS1
                983     ;
1288 B6 5A      984          LDA   VS2         ;ADD VS2
128A A9 00      985          ADC   #$00
128C 8D         986          DAA             ;DECIMAL ADHUST RESULT
128D B7 5A      987          STA   VS2         ;STORE RESULT
128F 81         988     ENDCALC RTS
                989     ;
                990     $EJECT
```

```
                    991     ;
                    992     ;                   TIMING THE MOTOR
                    993     ;-----------------------------------------------------------------
                    994     ;     This routine compares the calculated vs. timed motor on time and restarts
                    995     ;       the motor every time they are equal.
                    996     ;       The motor is turned off in the rpm routine>
                    997     ;       the calculated values are generated by the UPDATE subroutine.
                    998     ;
                    999     ;       Variables: MOTIM1=INCREMENTED EACH TIME
                   1000     ;                  MOTIM2=INCREMENTED EACH TIME MOTIM1 OVERFLOWS
                   1001     ;                  TIMLO= CALCULATED FIRST BYTE OF TIME ON GENERATED IN UPDATE
                   1002     ;                  TIMHI= CALCULATED SECOND BYTE OF TIME
                   1003     ;
                   1004     ;        Conditions
                   1005     ;
1290 05 6D 29      1006     MOTCK BRCLR 2,PSTAT1,END1   ;DONT DO IF UNIT OFF
1293 00 6D 26      1007           BRSET 0,PSTAT1,END1    ;DON'T DO IF HOLD
                   1008     ;     BRSET 7,ERRON,END1     ;DON'T DO IF ERROR MODE
                   1009     ;     BRSET 3,PSTAT1,END1    ;DONT DO IF START MODE
                   1010     ;
                   1011     ;          ABOVE LINES DELETED TO ALLOW MOTOR TO
                   1012     ;          PUMP WITH LO BAT ERROR
```

```
                    1013    ;
                    1014    ;
                    1015    ;       Check if time running equals time calculated
                    1016    ;
1296 98             1017            CLC
1297 B6 7D          1018            LDA   MOTIM1
1299 AB 01          1019            ADD   #$01
129B B7 7D          1020            STA   MOTIM1
129D 25 0D          1021            BCS   INCM2
129F B6 47          1022    BACK    LDA   TIMLO
12A1 B1 7D          1023            CMP   MOTIM1
12A3 26 17          1024            BNE   END1
12A5 B6 48          1025            LDA   TIMHI
12A7 B1 7E          1026            CMP   MOTIM2
12A9 27 07          1027            BEQ   MOTON
12AB 81             1028            RTS
                    1029    ;
12AC 98             1030    INCM2   CLC
12AD 3C 7E          1031            INC   MOTIM2
12AF CC 129F        1032            JMP   BACK
                    1033    ;
                    1034    ;       Times are equal so turn motor on again
```

```
                    1035    ;
12B2 12 6D          1036    MOTON BSET  1,PSTAT1    ;MOTOR ON FLAG
12B4 1A 01          1037          BSET  5,PORTB          ;TURN MOTOR ON
12B6 3F 7B          1038          CLR   THIRDR           ;CLR  THIRD OF A REV COUNTER
12B8 3F 7D          1039          CLR   MOTIM1           ;RESET POINTER
12BA 3F 7E          1040          CLR   MOTIM2           ;
12BC 81             1041    END1  RTS
                    1042    ;
                    1043    ;
                    1044    $EJECT
```

```
                    1045    ;
                    1046    ;
                    1047    ;                    SET CHECK
                    1048    ;-------------------------------------------------------------------
                    1049    ;       Conditions
                    1050    ;
12BD 05 6D 19       1051    SETCK BRCLR 2,PSTAT1,NOSCK   ;DONT DO IF UNIT OFF
12C0 06 6D 16       1052          BRSET 3,PSTAT1,NOSCK   ;DONT DO IF UNIT IS IN START MODE
12C3 00 6D 13       1053          BRSET 0,PSTAT1,NOSCK   ;DONT DO IF UNIT IS IN HOLD
                    1054    ;
                    1055    ;     CHECK FOR PROPER SET PLACEMENT
                    1056    ;
12C6 07 02 10       1057          BRCLR 3,PORTC,NOSCK    ;IF SET PRESENT, RETURN
                    1058    ;                            ;ELSE SET ERROR
12C9 18 6E          1059               BSET  4,NOSET     ;ENABLE SET ERROR FLAG
12CB 1E 6E          1060          BSET  7,ERRON          ;ENABLE ERROR MODE
12CD 1A 6E          1061          BSET  5,ALRM           ;ENABLE AUDIO ALARM
12CF 1D 6E          1062          BCLR  6,VOLM             ;GET OUT OF VOLUME MODE
12D1 11 71          1063          BCLR  0,DFLAG          ;CLEAR DOSE MODE FLAG
12D3 13 6D          1064          BCLR    1,PSTAT1 ;CLEAR MOTOR ON FLAG
12D5 1B 01          1065          BCLR  5,PORTB          ;TURN OFF MOTOR
12D7 10 6D          1066          BSET  0,PSTAT1   ;SET HOLD FLAG TO DISABLE MOTCK
```

```
                  ;
12D9 81           NOSCK RTS



                  $EJECT
```

```
                    1074    ;
                    1075    ;
                    1076    ;                   INPUTING THE RATE (model 224)
                    1077    ;-----------------------------------------------------------------
                    1078    ;         Conditions
                    1079    ;
12DA 05 6D 40       1080    INRATE1     BRCLR 2,PSTAT1,OVER     ;DONT DO IF OFF
12DD 00 80 3D       1081          BRSET 0,DSPTST,OVER     ;DONT DO IF TEST MODE
12E0 00 6E 3A       1082          BRSET 0,LOWBAT,OVER     ;DONT DO IF LOWBAT
12E3 0E 6E 37       1083          BRSET 7,ERRON,OVER      ;DONT DO IF ERROR MODE
12E6 0E 6D 34       1084          BRSET 7,PSTAT1,OVER     ;DONT DO IF MODEL 324
12E9 06 6D 03       1085          BRSET 3,PSTAT1,CKRTE    ;IF START MODE DO
12EC 01 6D 2E       1086          BRCLR 0,PSTAT1,OVER   ;DONT DO IN HOLD OFF MODE
                    1087    ;
                    1088    ;     DECODE RATE SWITCH
                    1089    ;
12EF 38 82          1090    CKRTE LSL   LSTRAT            ;SHIFT LSTRAT LEFT 2 BITS
12F1 38 82          1091          LSL   LSTRAT
12F3 B6 02          1092          LDA   PORTC       ;GET AND MASK CURRENT KNOB POSITION
12F5 A4 03          1093          AND   #$03
12F7 BA 82          1094          ORA   LSTRAT          ;MERGE PREVIOUS AND CURRENT POSITIONS
12F9 A4 0F          1095          AND   #$0F        ;MASK OUT UPPER NIBBLE
```

```
12FB B7 82      1096          STA   LSTRAT          ;STORE RATE POSITION FOR NEXT TIME
                1097    ;
12FD A1 01      1098          CMP   #$01       ;BEGIN DECODING DEC POSITIONS
12FF 27 64      1099          BEQ   DECR1
1301 A1 07      1100          CMP   #$07
1303 27 60      1101          BEQ   DECR1
1305 A1 08      1102          CMP   #$08
1307 27 5C      1103          BEQ   DECR1
1309 A1 0E      1104          CMP   #$0E
130B 27 58      1105          BEQ   DECR1
                1106    ;
130D A1 02      1107          CMP   #$02       ;BEGIN DECODING INC POSITIONS
130F 27 0D      1108          BEQ   INCR1
1311 A1 04      1109          CMP   #$04
1313 27 09      1110          BEQ   INCR1
1315 A1 0B      1111          CMP   #$0B
1317 27 05      1112          BEQ   INCR1
1319 A1 0D      1113          CMP   #$0D
131B 27 01      1114          BEQ   INCR1
131D 81         1115    OVER  RTS
                1116
                1117    ;           test for increase by one
```

```
                1118    ;
131E 1B 74      1119    INCR1 BCLR  5,ZEROST    ;CLEAR DISPLAY ZERO FLAG
1320 16 6D      1120          BSET  3,PSTAT1    ;MAKE START ON
1322 18 6D      1121          BSET  4,PSTAT1    ;MAKE DISPLAY ON
1324 A6 03      1122          LDA   #$03        ;IF 300, RETURN
1326 B1 53      1123          CMP   DSPDG3
1328 27 F3      1124          BEQ   OVER
                1125    ;
132A 0F 6D 1A   1126          BRCLR 7,PSTAT1,UPFIVE   ;IF MODEL 224 GO UP BY 5 ONLY
                1127    ;
                1128    ;                       ;IF RATE >= 50, INCREMENT BY 5
132D B6 53      1129          LDA   DSPDG3            ;
132F 26 16      1130          BNE   UPFIVE            ;IF DIGIT 3 IS NOT 0, INCREMENT BY 5
1331 B6 52      1131          LDA   DSPDG2
1333 A1 05      1132          CMP   #$05
1335 24 10      1133          BHS   UPFIVE            ;IF DIGIT 2 IS >= 5, INCREMENT BY 5
                1134    ;
1337 98         1135    UPONE CLC               ;ELSE INCREMENT BY 1
1338 A6 F7      1136          LDA   #$F7        ;TEST FOR 9
133A BB 51      1137          ADD   DSPDG1
133C 25 05      1138          BCS   DEC91       ;IF 9 MAKE 0 AND INC NEXT DIGIT
133E 3C 51      1139          INC   DSPDG1            ;IF NOT THEN INC BY ONE
```

```
1340 CC 1756      1140          JMP   UPDATE
                  1141    ;
1343 3F 51        1142    DEC91 CLR   DSPDG1
1345 20 09        1143          BRA   INC2
                  1144    ;
                  1145    ;        increment by five
                  1146    ;
                  1147    ;
1347 CD 174B      1148    UPFIVE      JSR   TOGGLE          ;ELSE INCR BY 5
134A A6 05        1149          LDA   #$05
134C B1 51        1150          CMP   DSPDG1
134E 27 12        1151          BEQ   DEC3
                  1152    ;
                  1153    ;       Increment digit 2 by one
                  1154    ;
1350 98           1155    INC2  CLC             ;IF DIGITB IS 9 THEN GO MAKE IT 0
1351 A6 F7        1156          LDA   #$F7      ;ADD 255-8 TO DIGITB
1353 BB 52        1157          ADD   DSPDG2          ;IF OVER FLOW THEN MAKE 0
1355 25 05        1158          BCS   DEC9
1357 3C 52        1159          INC   DSPDG2          ;IF OK THEN DIGIT=DIGIT+1
1359 CC 1756      1160          JMP   UPDATE          ;NOW GO DO DIGIT3
135C 3F 52        1161    DEC9  CLR   DSPDG2          ;DIGIT2=0
```

```
                1162    ;
                1163    ;       Increment digit 3 by one
                1164    ;
135E 3C 53      1165    INC3  INC     DSPDG3
1360 1F 74      1166          BCLR  7,ZEROST
1362 CC 1756    1167    DEC3  JMP     UPDATE
                1168    ;
                1169    ;       Do a rate decrease
                1170    ;
                1171    ;       test for decrement by 5
                1172    ;
1365 16 6D      1173    DECR1 BSET  3,PSTAT1    ;MAKE START ON
1367 18 6D      1174          BSET  4,PSTAT1    ;MAKE DISPLAY ON
1369 0A 74 B1   1175          BRSET 5,ZEROST,OVER     ;IF DISPLAY IS 0 THEN DONT DECR
136C B6 53      1176          LDA   DSPDG3            ;PREPARE ACCA FOR ZERO TEST OF
136E BA 52      1177          ORA   DSPDG2            ;DSPDG2 AND DSPDG3
1370 0E 6D 03   1178          BRSET 7,PSTAT1,CH324    ;IF 324 GOTO CH324, ELSE
1373 26 62      1179    CH224 BNE   DECR5       ;IF 224 AND DIGIT 2 & 3 ARE NOT ZERO, DECR5
1375 81         1180          RTS               ;ELSE DONT DECR
                1181    ;
1376 26 07      1182    CH324 BNE   DECCN       ;IF DIGIT2 & 3 ARE NOT ZERO, CONTINUE
1378 B6 51      1183          LDA   DSPDG1            ;ELSE, TEST DIGIT 1 FOR 1
```

```
137A A1 01      1184          CMP   #$01
137C 26 13      1185          BNE   DOWN1       ;IF NOT 1,DECR BY 1
137E 81         1186          RTS
                1187    ;
137F B6 53      1188    DECCN LDA   DSPDG3            ;IF DIGIT3 NOT ZERO,
1381 26 54      1189          BNE   DECR5       ;DECR BY 5
1383 B6 52      1190          LDA   DSPDG2            ;IF DIGIT2 > 5,
1385 A1 05      1191          CMP   #$05        ;
1387 22 4E      1192          BHI   DECR5       ;DECR BY 5
1389 25 06      1193          BLO   DOWN1       ;ELSEIF DIGIT2 < 5 DECR BY 1
138B B6 51      1194          LDA   DSPDG1            ;ELSE TEST DIGIT1
138D A1 00      1195          CMP   #$00        ;IF DIGIT1 NOT ZERO,
138F 26 46      1196          BNE   DECR5       ;DECR BY 5
                1197
                1198    ;
                1199    ;     DECREMENT BY 1
                1200    ;
1391 B6 51      1201    DOWN1       LDA   DSPDG1            ;GET DIGIT 1
1393 27 09      1202          BEQ   TET2        ;IF ZERO THEN MAKE 9
1395 A1 01      1203          CMP   #$01
1397 27 34      1204          BEQ   CHK300
1399 3A 51      1205    DEC2  DEC   DSPDG1            ;IF NOT THEN JUST DECREMENT
```

```
139B CC 1756      1206          JMP   UPDATE          ;GO UPDATE THE RATE
                  1207    ;
139E B6 52        1208    TET2  LDA   DSPDG2
13A0 26 0B        1209          BNE   INC9A
13A2 3A 53        1210          DEC   DSPDG3
13A4 A6 09        1211          LDA   #$09
13A6 B7 51        1212          STA   DSPDG1
13A8 B7 52        1213          STA   DSPDG2
13AA CC 1756      1214          JMP   UPDATE
                  1215    ;
13AD 3A 52        1216    INC9A DEC   DSPDG2         ;IF NOT DECREMENT BY ONE
13AF A6 09        1217          LDA   #$09      ;MAKE FIRST DIGIT 9
13B1 B7 51        1218          STA   DSPDG1
13B3 CC 1756      1219          JMP   UPDATE          ;GO UPDATE THE DISPLAY
                  1220    ;
13B6 A6 03        1221    GO300 LDA   #$03      ;CHANGE DIGIT 3 TO 3
13B8 B7 53        1222          STA   DSPDG3
13BA A6 00        1223          LDA   #$00      ;MAKE DISPLAY 300
13BC B7 52        1224          STA   DSPDG2
13BE B7 51        1225          STA   DSPDG1
                  1226    ;     CLR   ZEROST
13C0 B6 78        1227          LDA   SPEED1
```

```
13C2 A1 40      1228            CMP   #$40
13C4 25 04      1229            BLO   SPDY1
13C6 A6 41      1230            LDA   #$41
13C8 B7 78      1231            STA   SPEED1
13CA CC 1756    1232      SPDY1 JMP   UPDATE
                1233      ;
13CD B6 52      1234      CHK300      LDA   DSPDG2          ;IF DIGIT 2 IS ZERO MAKE 300
13CF 26 C8      1235            BNE   DEC2
13D1 B6 53      1236            LDA   DSPDG3
13D3 26 C4      1237            BNE   DEC2
13D5 20 DF      1238            BRA   GO300
                1239      ;
                1240      ;           change rate by 5
                1241      ;
13D7 4F         1242      DECR5 CLRA
13D8 B1 53      1243            CMP   DSPDG3          ;IF DIGIT 2,3 ARE 0 THEN MAKE 000
13DA 26 0D      1244            BNE   TOG2
13DC B1 52      1245            CMP   DSPDG2
13DE 26 09      1246            BNE   TOG2
13E0 B7 51      1247            STA   DSPDG1
13E2 A6 03      1248            LDA   #$03
13E4 B7 53      1249            STA   DSPDG3
```

```
                1250    ;       CLR   ZEROST
13E6 CC 1756    1251            JMP     UPDATE
13E9 CD 174B    1252    TOG2    JSR     TOGGLE          ;GO MAKE 0 OR 5
13EC A6 00      1253            LDA   #$00
13EE B1 51      1254            CMP   DSPDG1
13F0 27 19      1255            BEQ   INCD3
                1256    ;
                1257    ;         Decrement digit 2 by one
                1258    ;
13F2 B6 52      1259            LDA   DSPDG2            ;GET POINTER
13F4 27 05      1260            BEQ   INC9        ;IF 0 THEN MAKE 9
13F6 3A 52      1261            DEC   DSPDG2            ;IF>0 THEN SUB 1
13F8 CC 1756    1262    SETZ    JMP   UPDATE            ;GO DO DIGIT 3
13FB B6 53      1263    INC9    LDA   DSPDG3
13FD 27 0C      1264            BEQ   INCD3
13FF A6 09      1265            LDA   #$09        ;RESET TO 9
1401 B7 52      1266            STA   DSPDG2
                1267    ;
                1268    ;         Decrement digit 3 by one
                1269    ;
1403 B6 53      1270    DECD3   LDA   DSPDG3            ;GET DIGIT 3 POINTER
1405 27 04      1271            BEQ   INCD3       ;IF 0 THEN MAKE 2
```

```
1407 3A 53          1272            DEC   DSPDG3          ;>0 SO SUB 1
1409 1F 74          1273            BCLR  7,ZEROST
140B CC 1756        1274      INCD3 JMP     UPDATE
                    1275      ;
                    1276      ;
                    1277      $EJECT
```

```
                    1278    ;
                    1279    ;
                    1280    ;                       OFF CHECK
                    1281    ;-------------------------------------------------------------------
                    1282    ;         Conditions
                    1283    ;
140E 05 6D 2C       1284    OFFCK   BRCLR    2,PSTAT1,TSTCK  ;IF OFF, CHECK IF TIME FOR TEST MODE
1411 05 02 01       1285            BRCLR    2,PORTC,GOFF    ;IF OFF BUTTON PRESSED GO OFF
1414 81             1286    NOOFF   RTS
                    1287    ;
                    1288    ;         Do off
                    1289    ;
1415 00 6E 1E       1290    GOFF    BRSET 0,LOWBAT,KILLP1   ;IF LOW BATT KILL POWER
1418 3F 6E          1291            CLR    PSTAT2           ;NO ALARMS OR OPTIONAL MODES
141A 3F 71          1292            CLR    DFLAG        ;CLEAR DOSE FLAG
141C 3F 80          1293            CLR    DSPTST           ;CLEAR DISPLAY TEST FLAG
                    1294    ;
141E A6 19          1295            LDA    #$19         ;SET PSTAT1 FOR NEXT TURN-ON
1420 B7 6D          1296            STA    PSTAT1
1422 A6 1F          1297            LDA    #$1F             ;KILL DISPLAY AND MOTOR  0001 1111 OR
1424 B7 01          1298            STA    PORTB
1426 CD 1948        1299            JSR    TIMRST           ;CLEAR ALL TIMERS FOR 24HR KEEPING
```

```
1429 3F 45              CLR   T25
142B 3F 55              CLR   DS1         ;CLEAR DS1 AND DS2 FOR USE AS
142D 3F 56              CLR   DS2         ;3 SEC TEST TIMER.
142F 8F          LOOPF        WAIT                  ; GO SLEEP
1430 20 FD              BRA   LOOPF
                 ;
                 ;      wake up by on button (external int)
                 ;
1432 CD 1106            JSR   TIMEON            ;RESET COUNTER TIMER
1435 81                 RTS
                 ;
1436 9B          KILLP1       SEI                 ;SET INT MASK TO PREVENT TURN-ON
1437 A6 0F              LDA   #$0F        ;DISABLE PUMP
1439 B7 01              STA   PORTB
143B 20 F9              BRA   KILLP1              ;LOOP UNTILL POWER DISSIPATES
                 ;
                 ;      TEST CHECK
                 ;
143D 04 02 03    TSTCK BRSET 2,PORTC,TSTOUT   ;IF OFF BUTTON NOT PUSHED, RETURN
1440 05 03 05           BRCLR 2,PORTD,TSTCNT  ;ELSE, IF HOLD BUTTON PRESSED INCREMENT
                 ;                            ; TES COUNTER
1443 3F 55       TSTOUT  CLR DS1
```

```
1445 3F 56          1322            CLR   DS2
1447 81             1323            RTS
                    1324    ;
1448 3C 55          1325    TSTCNT  INC   DS1         ;INCREMENT TEST TIMER
144A 26 02          1326            BNE   TST1
144C 3C 56          1327            INC   DS2
144E B6 56          1328    TST1    LDA   DS2         ;IF 3 SEC ELAPSED, GOTO PMPTST
1450 A1 02          1329            CMP   #$02
1452 24 01          1330            BHS   PTST
1454 81             1331            RTS               ;ELSE RETURN
1455 CC 1C00        1332    PTST    JMP   PMPTST
                    1333    ;
                    1334    $EJECT
```

```
                1335    ;
                1336
                1337    ;                       TEST MODE
                1338    ;-------------------------------------------------------------------
                1339    ;
1458 05 6D 30   1340    TESTD BRCLR 2,PSTAT1,NOTST    ;DONT DO IF UNIT OFF
145B 01 80 2D   1341          BRCLR 0,DSPTST,NOTST    ;DONT DO IF TEST FLAG NOT SET
145E 0F 6D 2D   1342          BRCLR 7,PSTAT1,TSTD2    ;IF 224, DO SHORT TEST MODE
1461 3C 79      1343          INC   VOLTIM            ;DO FOR .033*60=1.98 SEC
1463 B6 79      1344          LDA   VOLTIM
1465 A1 78      1345          CMP   #120        ;GO CLEAR TEST MODE
1467 22 4F      1346          BHI   CLTEST
1469 A1 64      1347          CMP   #100        ;GO DISPLAY DOSE NUMBER
146B 22 7B      1348          BHI   DOSDIS
146D A1 50      1349          CMP   #80         ;GO DISPLAY DOSE
146F 22 66      1350          BHI   DOSTST
1471 A1 3C      1351          CMP   #60         ;GO DISPLAY VOLUME NUMBER
1473 22 5E      1352          BHI   VOLDS
1475 A1 28      1353          CMP   #40         ;GO DISPLAY VOL
1477 22 49      1354          BHI   VOLTST
1479 A1 14      1355          CMP   #20         ;GO KILL ALARM FIRST
147B 22 22      1356          BHI   CLATST
```

EP 0 327 209 A2

```
147D 1E 01      1357    CONTST  BSET  7,PORTB         ;ALARM ON
147F 1C 01      1358            BSET  6,PORTB         ;CLEAR LED ON
1481 1C 6E      1359            BSET  6,VOLM          ;SET VOLM FLAG TO ENABL 4 DIGITS
1483 3F 4D      1360            CLR   SAMPL1          ;MAKE DISPLAY "8888"
1485 3F 4E      1361            CLR   SAMPL2
1487 3F 4F      1362            CLR   SAMPL3
1489 3F 50      1363            CLR   SAMPL4
148B 1D 03      1364    NOTST   BCLR  6,PORTD         ;TURN IR SOURCE OFF
148D 81         1365            RTS
                1366    ;
                1367    ;       SHORT TEST FOR K224
                1368    ;
148E 1C 6E      1369    TSTD2   BSET  6,PSTAT2    ;VOLUME FLAG SET TO ENABLE 4 DIGITS
1490 3C 79      1370            INC   VOLTIM          ;DO FOR .033*60=1.98 SEC
1492 B6 79      1371            LDA   VOLTIM
1494 A1 3C      1372            CMP   #$3C
1496 22 20      1373            BHI   CLITEST
1498 A1 14      1374            CMP   #$14
149A 22 03      1375            BHI   CLATST
149C CC 147D    1376            JMP   CONTST
                1377    ;
                1378
```

```
149F 1F 01          1379    CLATST    BCLR  7,PORTB          ;TURN ALARM OFF
14A1 1D 01          1380          BCLR  6,PORTB          ;LED OFF
                    1381    ;
                    1382    ;         test sensor eyes
                    1383    ;
14A3 1C 03          1384          BSET  6,PORTD          ;TURN IR SOURCE ON
14A5 9D             1385          NOP             ;ADD 8 USEC DELAY TO ALLOW IR
14A6 9D             1386          NOP             ;SENSOR TO SETTLE
14A7 9D             1387          NOP
14A8 9D             1388          NOP
14A9 0A 02 DF       1389          BRSET 5,PORTC,NOTST    ;IF RECIEVER LOW EYES BLOCKED THEN ERROR
14AC 1D 03          1390          BCLR  6,PORTD          ;TURN OFF IR SOURCE
14AE 1A 6E          1391          BSET  5,PSTAT2    ;ENABLE ALARM
14B0 14 6E          1392          BSET  2,NDROP     ;ENABLE FLOW ERROR FLAG
14B2 1E 6E          1393          BSET  7,PSTAT2    ;ENABLE     ERROR FLAG
14B4 1F 01          1394          BCLR  7,PORTB          ;TURN ALARM OFF
14B6 17 6D          1395          BCLR  3,PSTAT1    ;CLEAR START FLAG
                    1396    ;
14B8 CD 1756        1397    CLITEST   JSR   UPDATE           ;RESTORE DISPLAY
14BB 3F 80          1398          CLR   DSPTST           ;CLEAR TEST FLAG
14BD 1D 6E          1399          BCLR  6,VOLM           ;CLEAR VOLUME FLAG FOR 224
14BF 3F 79          1400          CLR   VOLTIM           ;CLEAR TIMER
```

```
14C1 81          1401          RTS
                 1402     ;
14C2 A6 F8       1403     VOLTST    LDA  #$F8        ;
14C4 B7 50       1404          STA  SAMPL4
14C6 A6 9C       1405          LDA  #$9C
14C8 B7 4F       1406          STA  SAMPL3
14CA A6 C8       1407          LDA  #$C8
14CC B7 4E       1408          STA  SAMPL2
14CE A6 FF       1409          LDA  #$FF
14D0 B7 4D       1410          STA  SAMPL1
14D2 81          1411          RTS
                 1412     ;
14D3 CD 1634     1413     VOLDS JSR  VSEXP
14D6 81          1414          RTS
                 1415     ;
14D7 A6 B0       1416     DOSTST    LDA  #$B0
14D9 B7 50       1417          STA  SAMPL4
14DB A6 92       1418          LDA  #$92
14DD B7 4F       1419          STA  SAMPL3
14DF A6 9C       1420          LDA  #$9C
14E1 B7 4E       1421          STA  SAMPL2
14E3 A6 8C       1422          LDA  #$8C
```

```
14E5 B7 4D      1423          STA   SAMPL1
14E7 81         1424          RTS
                1425    ;
14E8 CD 1745    1426    DOSDIS      JSR   DSEXP       ;DISPLAY PROGRAMMED DOSE
14EB 81         1427          RTS
                1428
                1429
                1430    ;
                1431    $EJECT
```

```
                    1432    ;
                    1433    ;                   HOLD CHECK
                    1434    ;-----------------------------------------------------------------
                    1435    ;              Conditions
                    1436    ;
14EC 05 6D 43       1437    HOLDCK  BRCLR     2,PSTAT1,NOHOLD   ;IF OFF DONT DO
14EF 00 80 40       1438            BRSET 0,DSPTST,NOHOLD ;DONT DO IF TEST MODE
14F2 00 76 3D       1439            BRSET 0,CWF,NOHOLD      ;DONT DO IF INC OR DEC
14F5 00 77 3A       1440            BRSET 0,CCWF,NOHOLD     ;BUTTON IS PRESSED
                    1441    ;
14F8 04 03 38       1442            BRSET       2,PORTD,NOH1    ;IS HOLD BUTTON DOWN RETURN IF NOT
                    1443    ;
                    1444    ;              Hold  button down
                    1445    ;
                    1446    ;              Debounce switch
                    1447    ;
14FB 00 73 34       1448            BRSET   0,HTEST,NOHOLD ;WE MUST BE SEEING SAME PULSE SO IGNORE
14FE 10 73          1449            BSET  0,HTEST           ;IF NOT SAME SET THE FLAG
                    1450    ;
                    1451    ;           CLEAR HOLD TIME COUNTERS
                    1452    ;
1500 3F 4B          1453            CLR   HLDTM1
```

```
1502 3F 4C      1454            CLR   HLDTM2
                1455    ;
                1456    ;               Check for alarm conditions
                1457    ;
1504 00 6E 2F   1458            BRSET 0,LOWBAT,HLDBAT   ;IF LOW BAT,STOP ALARM AND MOTOR.
1507 00 70 37   1459            BRSET   0,DOSER,STDOSE  ;IF DOSE DEL FLAG SET, STOP DOSE MESS.
150A 0A 6E 2F   1460            BRSET 5,ALRM,NOAUDO     ;IF WE ARE ALARMING THEN KILL AUDIO
150D 0E 6E 3F   1461            BRSET 7,ERRON,NOMESS    ;IF WE ARE FLASHING ERROR MESSAGE THEN GO RUN
1510 0C 6E 34   1462            BRSET 6,VOLM,NOVOLM     ;IF IN VOL GO RESTORE RATE
1513 00 71 35   1463            BRSET 0,DFLAG,NODOS     ;IF DOSE MODE, GO RESTORE RATE
                1464    ;
                1465    ;               Are we in hold now run if yes, hold if not
1516 06 6D 3E   1466            BRSET 3,PSTAT1,RUN      ;IF IN START MODE THEN DO RUN
                1467    ;
1519 00 6D 3B   1468            BRSET 0,PSTAT1,RUN      ;IF YES GO RUN
151C 10 6D      1469    HOLD    BSET  0,PSTAT1    ;IF NOT SET HOLD FLAG
151E 1B 01      1470            BCLR  5,PORTB           ;MOTOR OFF
1520 13 6D      1471            BCLR  1,PSTAT1    ;CLEAR MOTOR ON FLAG
                1472    ;
1522 B6 02      1473            LDA   PORTC       ;RE-INITIALIZE RATE KNOB
1524 A4 03      1474            AND   #$03
1526 B7 82      1475            STA   LSTRAT
```

```
                    1476    ;
1528 3F 6E          1477          CLR   PSTAT2
152A 3F 70          1478          CLR   DOSER       ;CLR DOSE ERROR FLAG
152C CD 1756        1479          JSR   UPDATE          ;RESTORE DIGITS TO KILL SCROLLING DP
152F CD 1948        1480          JSR   TIMRST
1532 81             1481    NOHOLD      RTS
                    1482    ;
                    1483    ;         Hold button not down so reset the flag and return
                    1484    ;
1533 11 73          1485    NOH1  BCLR  0,HTEST
1535 81             1486          RTS
                    1487    ;
                    1488    ;         LOW BAT HOLD
                    1489    ;
                    1490    ;           kill motor
                    1491    ;
1536 13 6D          1492    HLDBAT      BCLR  1,PSTAT1    ;CLEAR MOTOR ON FLAG
1538 1B 01          1493          BCLR  5,PORTB           ;TURN MOTOR OFF
153A 10 6D          1494          BSET  0,PSTAT1    ;SET HOLD FLAG
                    1495    ;
                    1496    ;         AND
                    1497    ;
```

```
                1498    ;            Kill the audio
                1499    ;
153C 1B 6E      1500    NOAUDO      BCLR  5,ALRM           ;RESET BEEPER FLAG
153E 1F 01      1501          BCLR  7,PORTB          ;STOP AUDIO NOW
1540 81         1502          RTS
                1503    ;
                1504    ;          STOP DOSE DELIVIRED MESSAGE
                1505    ;
1541 1D 6E      1506    STDOSE      BCLR  6,VOIM           ;CLEAR ALARM FLAG
1543 1F 01      1507          BCLR  7,PORTB          ;STOP ALARM
1545 20 D5      1508          BRA   HOLD        ;PUT PUMP IN HOLD
                1509    ;
                1510    ;            Recovery from error KILL THE MESSAGE
                1511    ;
1547 1D 6E      1512    NOVOLM      BCLR  6,VOIM
1549 20 D1      1513          BRA   HOLD
                1514    ;
154B 11 71      1515    NODOS BCLR  0,DFLAG
154D 20 CD      1516          BRA   HOLD
                1517    ;
                1518    ;
154F 3F 6E      1519    NOMESS  CLR PSTAT2
```

```
1551 CD 1756    1520            JSR   UPDATE          ;RESTORE DISPLAY TO RATE
1554 CC 1557    1521            JMP   RUN         ;GO RUN MOTOR
                1522    ;
                1523    ;
                1524    ;
                1525    ;------------------------------ RUN MOTOR PUMPING ----------------------
                1526    ;
                1527    ;
1557 17 6D      1528    RUN     BCLR  3,PSTAT1    ;SET UNIT START OFF
1559 18 6D      1529            BSET  4,PSTAT1        ;SET DISPLAY ON
                1530    ;
155B B6 55      1531            LDA   DS1         ;CHECK IF DOSE DEL BEFORE TURNING
155D BA 56      1532            ORA   DS2         ;MOTOR ON
155F 27 16      1533            BEQ   RUN1        ;IF DOSE = 0, NO NEED TO CHECK
1561 CD 1951    1534            JSR   CPVTOD            ;ELSE, CALL CMP VOL TO DOSE ROUTINE
1564 A3 FF      1535            CPX   #$FF        ;X IS FF IF VOL >= DOSE
1566 26 0F      1536            BNE   RUN1        ;IF X != FF, OK TO START MOTOR
                1537    ;
1568 10 70      1538            BSET  0,DOSER           ;ELSE, SET DOSE DEL MESSAGE
156A 10 6D      1539            BSET  0,PSTAT1    ;SET HOLD FLAG TO DISABLE MOTCK
156C 1E 6E      1540            BSET  7,ERRON           ;ENABLE ERROR FLAG
156E 1A 6E      1541            BSET  5,ALRM            ;ENABLE ALARM
```

```
1570 1D 6E      1542            BCLR  6,VOLM          ;CLEAR VOL MODE FLAG
1572 11 71      1543            BCLR  0,DFLAG         ;CLEAR DOSE MODE FLAG
1574 19 6E      1544            BCLR  4,NOSET         ;CLR NO SET FLAG
1576 81         1545            RTS
                1546      ;
                1547      ;
1577 3F 7D      1548      RUN1  CLR   MOTIM1
1579 3F 7E      1549            CLR     MOTIM2
157B 3F 81      1550            CLR     COUNT4
157D 3F 63      1551            CLR     COUNT2
157F 3F 5B      1552            CLR     REG1
1581 3F 5D      1553            CLR     DRCNT1
1583 3F 5E      1554            CLR   DRCNT2
1585 3F 5F      1555            CLR   REG3
1587 3F 60      1556            CLR   REG4
1589 3F 61      1557            CLR   REG5
158B 3F 7A      1558            CLR   THIRD1
158D 3F 7B      1559            CLR   THIRDR
158F 3F 7F      1560            CLR   ERRCNT
1591 3F 6E      1561            CLR   PSTAT2
                1562      ;     LDA   #$10
                1563      ;     STA   PSTAT2
```

```
                1564    ;
1593 B6 51      1565            LDA   DSPDG1            ;CHECK RATE VALUE
1595 BA 52      1566            ORA   DSPDG2
1597 BA 53      1567            ORA   DSPDG3
1599 BA 54      1568            ORA   DSPDG4
159B 26 05      1569            BNE   RUNMOT            IF RATE!=0, RUNMOT
                1570    ;       BSET  7,ERRON             ;IT =000 SO SET ERROR BIT
159D 1A 6E      1571            BSET  5,ALRM            ;SET ALARM BIT
159F 10 6D      1572            BSET  0,PSTAT1
                1573    ;       BCLR  0,PSTAT1
15A1 81         1574            RTS                      ;AND RETURN
15A2 12 6D      1575    RUNMOT  BSET  1,PSTAT1    ;MOTOR ON FLAG
15A4 11 6D      1576            BCLR  0,PSTAT1    ;RUN FLAG ON
15A6 1A 01      1577            BSET  5,PORTB           ;MOTOR ON
15A8 81         1578            RTS
                1579    ;
                1580
                1581
                1582    $EJECT
```

```
                    1583    ;          DOSE CHECK
                    1584    ; ------------------------------------
                    1585    ;         Conditions
                    1586    ;
15A9 05 6D 21       1587    DOSECK      BRCLR 2,PSTAT1,NDOSE   ;DON'T DO IF UNIT IS OFF
15AC 00 80 1E       1588          BRSET 0,DSPTST,NDOSE   ;DON'T DO IF TEST MODE
15AF 0F 6D 1B       1589          BRCLR 7,PSTAT1,NDOSE   ;DON'T DO IF UNIT IS 224
15B2 0E 6E 18       1590          BRSET 7,PSTAT2,NDOSE   ;DON'T DO IF ERROR MODE ON
                    1591    ;
15B5 00 71 0A       1592          BRSET 0,DFLAG,DOS1     ;IF DOSE FLAG SET THEN DOS1
                    1593    ;
15B8 00 76 12       1594          BRSET 0,CWF,NDOSE ;IF INC OR DEC FLAG PRESSED
15BB 00 77 0F       1595          BRSET 0,CCWF,NDOSE     ;DONT SET UP DOSE FEATURE
                    1596    ;
15BE 03 03 0D       1597          BRCLR 1,PORTD,SETDOS   ;IF DOSE BUTTON PUSHED THEN
                    1598                                 ;INITIALIZE DOSE MODE
15C1 81             1599          RTS                    ;ELSE RETURN
                    1600    ;
15C2 3C 57          1601    DOS1  INC   DOSECT
15C4 B6 57          1602          LDA   DOSECT
15C6 A1 1E          1603          CMP   #30
15C8 22 13          1604          BHI   DOS2
```

```
15CA CD 14D7    1605          JSR   DOSTST
15CD 81         1606    NDOSE RTS
                1607    ;
15CE 10 71      1608    SETDOS      BSET  0,DFLAG      ;SET DOSE MODE FLAG
15D0 1D 6E      1609          BCLR  6,VOLM            ;CLEAR VOLUME FLAG
                1610    ;
15D2 01 6D 04   1611          BRCLR 0,PSTAT1,CONDO    ;IF PUMP IN HOLD,
15D5 16 6D      1612          BSET  3,PSTAT1    ;SET START FLAG TO DISABLE FLASH
15D7 18 6D      1613          BSET  4,PSTAT1    ;MAKE DISPLAY ON
                1614                            ;ELSE, JUST CONTINUE WITH DOSE
15D9 3F 57      1615    CONDO CLR   DOSECT            ;CLEAR DOSE COUNTER
15DB 20 E5      1616          BRA   DOS1        ;CONTINUE DOSE HANDLING
                1617    ;
15DD CD 1745    1618    DOS2  JSR   DSEXP
15E0 B6 57      1619          LDA   DOSECT
15E2 A1 78      1620          CMP   #120
15E4 25 E7      1621          BLO   NDOSE
15E6 CD 1756    1622          JSR   UPDATE
15E9 11 71      1623          BCLR  0,DFLAG     ;NO DOSE MODE
15EB 3F 57      1624          CLR   DOSECT
15ED 81         1625          RTS
                1626    ;
```

1627 $EJECT

```
                    1628    ;
                    1629    ;         VOLUME DISPLAY CHECK
                    1630    ;-----------------------------------------------------------------
                    1631    ;        Conditions
                    1632    ;
15EE 05 6D 3C       1633    VOLDIS      BRCLR 2,PSTAT1,NVL      ;DONT DO IF OFF
15F1 00 80 39       1634          BRSET 0,DSPTST,NVL      ;DONT DO IF IN TEST MODE
15F4 0F 6D 36       1635          BRCLR 7,PSTAT1,NVL      ;DONT DO IF MODEL 224
                    1636    ;     BRSET 0,DFLAG,NVL ;DON'T DO IF IN DOSE MODE
15F7 0E 6E 33       1637          BRSET 7,ERRON,NVL ;DON'T DO IF ERROR MODE
15FA 00 76 30       1638          BRSET 0,CWF,NVL   ;DONT DO IF INC OR DEC BUTTON
15FD 00 77 2D       1639          BRSET       0,CCWF,NVL  ;IS PRESSED
                    1640    ;
1600 B6 59          1641          LDA   VS1         ;UPDATE CLEAR VOLUME LED.
1602 BA 5A          1642          ORA   VS2
1604 27 04          1643          BEQ   NOVLED
1606 1D 01          1644          BCLR  6,PORTB           ;TURN VOLUME LED OFF IF VOLUME NOT ZERO
1608 20 02          1645          BRA   VOLBUT1
160A 1C 01          1646    NOVLED      BSET  6,PORTB           ;IF NO VOLUME TURN ON LED
                    1647    ;
160C 0C 6E 11       1648    VOLBUT1     BRSET 6,VOLM,VOL1       ;IF VOL FLAG SET UPDATE DISPLAY
160F 07 03 01       1649          BRCLR 3,PORTD,SETVOL  ;IF VOL BUTTON PUSHED, INITIALIZE DISPLAY
```

```
1612 81          1650          RTS
                 1651     ;
1613 1C 6E       1652     SETVOL    BSET  6,VOLM          ;SET VOLUME DISPLAY MODE FLAG
1615 11 71       1653          BCLR  0,DFLAG          ;CLEAR DOSE FLAG
1617 3F 79       1654          CLR   VOLTIM           ;CLEAR VOLUME TIMER
1619 01 6D 04    1655          BRCLR 0,PSTAT1,VOL1    ;IF PUMP IN HOLD MODE,
161C 16 6D       1656          BSET  3,PSTAT1    ;SET START FLAG TO DISABLE FLASH
161E 18 6D       1657          BSET  4,PSTAT1    ;MAKE DISPLAY ON
                 1658                            ;ELSE, JUST CONTINUE VOLUME
                 1659     ;
1620 3C 79       1660     VOL1 INC   VOLTIM           ;INCREMENT VOLTIM
1622 B6 79       1661          LDA   VOLTIM
1624 A1 1E       1662          CMP   #30         ;IF ELAPSED TIME IS
1626 22 06       1663          BHI   VOL2        ; > 1.00 S, DISPLAY VOLUME
1628 CD 14C2     1664          JSR   VOLTST           ;ELSE DISPLAY VOLTST
162B 10 75       1665          BSET  0,VFLAG          ;SET VOL TEST DISPLAY FLAG
162D 81          1666     NVL  RTS
                 1667     ;
162E A1 78       1668     VOL2 CMP   #120        ;CHECK ELAPSED TIME, ACCA LOADED
                 1669                            ;WITH VOLTIM IN VOL1 ROUTINE
1630 22 08       1670          BHI   ENDVOL           ;IF TIME > 5 SEC, END VOL MODE
                 1671     ;
```

```
1632 11 75          1672          BCLR  0,VFLAG          ;CLEAR VOL TEST DISPLAY FLAG
                    1673    ;
1634 AE 59          1674    VSEXP LDX   #VS1        ;SET POINTER TO VS1 ADDRESS
1636 CD 19E7        1675          JSR   BCDEXP
1639 81             1676          RTS
                    1677    ;
163A CD 1756        1678    ENDVOL      JSR   UPDATE          ;RETURN DISPLAY TO RATE
163D 1D 6E          1679          BCLR  6,VOIM
163F 81             1680          RTS
                    1681    ;
                    1682    ;
                    1683    ;
                    1684    ;
                    1685    $EJECT
```

```
                    1686    ;
                    1687    ;
                    1688    ;
                    1689    ;                   CHECK CLEAR VOLUME BUTTON
                    1690    ;-----------------------------------------------------------------
                    1691    ;       Conditions
                    1692    ;
1640 05 6D 40       1693    CKCLR BRCLR 2,PSTAT1,NOCLR     ;DONT DO IF OFF
1643 00 80 3D       1694          BRSET 0,DSPTST,NOCLR    ;DONT DO IF IN TEST MODE
1646 0F 6D 3A       1695          BRCLR 7,PSTAT1,NOCLR     ;DONT DO IF MODEL 224
1649 00 83 24       1696          BRSET 0,CKBEP,CNALRM     ;IF ALARM ALREADY SET, HANDLE BEEP
                    1697    ;
                    1698    ;       Has volume clr button been pressed
                    1699    ;
164C 08 03 35       1700    CLR   BRSET 4,PORTD,NCLR1     ;IF CLR BUTTON NOT PRESSED RETURN
                    1701    ;
                    1702    ;     DEBOUNCE SWITCH
164F 02 73 31       1703          BRSET 1,HTEST,NOCLR     ;IF BUTTON SENSED LAST CYCLE, MUST BE
                    1704    ;                         ;SAME PULSE SO IGNORE
1652 12 73          1705          BSET  1,HTEST           ;ELSE SET FLAG FOR NEXT CYCLE
                    1706    ;
1654 0D 6E 2C       1707          BRCLR 6,VOLM,NOCLR      ;IF NOT VOLUME MODE, RETURN
```

```
                1708    ;
1657 B6 79      1709            LDA   VOLTIM            ;CHECK VOLTIM
1659 A1 1F      1710            CMP   #31          ;IF 'VOL' DISPLAY STILL ON
165B 23 26      1711            BLS   NOCLR        ;DON'T CLEAR YET
                1712    ;
                1713    ;       CHECK IF OK TO    CLEAR VOLUME
                1714    ;
165D B6 55      1715            LDA   DS1          ;IF DOSE = 0, CONTINUE CLEAR
165F BA 56      1716            ORA   DS2
1661 27 1A      1717            BEQ   CLR1
                1718    ;
1663 CD 1951    1719            JSR   CPVTOD            ;IF DOSE != 0 AND DOSE DEL.,
1666 A3 FF      1720            CPX   #$FF
1668 27 13      1721            BEQ   CLR1         ;IF X = FF, CONTINUE WITH CLEAR VOL
                1722    ;                          ;ELSE, ENABLE SHORT ALARM
166A 10 83      1723    CKALRM      BSET  0,CKBEP      ;SET CHECK ALARM BIT TO ENABLE BEEP
166C 3F 84      1724            CLR   CKTIM        ;INITIALIZE BEEP TIME
166E 1E 01      1725            BSET  7,PORTB           ;TURN ON ALARM
                1726    ;
1670 3C 84      1727    CNALRM      INC   CKTIM        ;INCREMENT BEEP TIMER
1672 B6 84      1728            LDA   CKTIM        ;CHECK IF TIME TO STOP BEEP
1674 A1 05      1729            CMP   #$05
```

```
1676 25 04          1730            BLO   CONBP       ;IF CKTIM <  AA, CONTINUE BEEP
1678 1F 01          1731            BCLR  7,PORTB           ;ELSE, TURN OFF BEEP
167A 11 83          1732            BCLR  0,CKBEP           ;CLEAR CK BEEP FLAG
167C 81             1733        CONBP RTS
                    1734        ;
                    1735        ;       CLEAR VOLUME
                    1736        ;
167D CD 1941        1737        CLR1    JSR CLVOL       ;CLEAR VOLUME
1680 CC 1634        1738            JMP   VSEXP
                    1739        ;
1683 81             1740        NOCLR RTS
                    1741        ;
1684 13 73          1742        NCLR1 BCLR  1,HTEST
1686 81             1743            RTS
                    1744        ;
                    1745        $EJECT
```

```
                    1746    ;
                    1747
                    1748    ;
                    1749    ;
                    1750    ;         Inputing the rate (model 324)
                    1751    ; ---------------------------------------------------
                    1752    ;
                    1753    ;        Conditions
                    1754    ;
1687 05 6D 23       1755    INRATE2     BRCLR 2,PSTAT1,OVER1    ;IF OFF DONT DO
168A 00 6E 20       1756          BRSET 0,LOWBAT,OVER1    ;DONT DO IF LOWBAT
168D 0E 6E 1D       1757          BRSET 7,ERRON,OVER1     ;DONT DO IF ERROR MODE
1690 0F 6D 1A       1758          BRCLR 7,PSTAT1,OVER1    ;IF MODEL 224 DONT DO
1693 00 80 17       1759          BRSET 0,DSPIST,OVER1    ;DONT DO IF IN TEST MODE
1696 0C 6E 14       1760          BRSET 6,VOLM,OVER1      ;DONT DO IF IN VOLUME DISPLAY
1699 06 6D 03       1761          BRSET 3,PSTAT1,CRTE     ;IF IN START MODE DO NOW
169C 01 6D 0E       1762          BRCLR 0,PSTAT1,OVER1    ;DON'T DO IN RUN MODE
                    1763    ;
                    1764    ;        Check for rate change
                    1765    ;
169F 03 02 12       1766    CRTE  BRCLR 1,PORTC,CCW1      ;IF BUTTON DOWN DO DECREASE
16A2 3F 77          1767          CLR   CCWF        ;CLEAR FLAG IF NOT DOWN
```

```
16A4 01 02 07    1768          BRCLR 0,PORTC,CW1 ;IF BUTTON DOWN GO INCREASE
16A7 3F 76       1769          CLR   CWF         ;CLEAR FLAG IF NOT DOWN
16A9 3F 78       1770          CLR   SPEED1
16AB 3F 7C       1771          CLR   OUTSPD
16AD 81          1772     OVER1 RTS               ;RETURN IF NO BUTTONS DOWN
                 1773     ;
                 1774     ;       Set flag to increase the rate
                 1775     ;
16AE 10 76       1776     CW1   BSET  0,CWF       ;SET FLAG FOR RATE INCREASE
16B0 CD 16BA     1777           JSR   SPEED       ;GO GET SPEED AND UPDATE
16B3 81          1778           RTS
                 1779     ;
                 1780     ;       Set flag to decrease the rate
                 1781     ;
16B4 10 77       1782     CCW1  BSET  0,CCWF          ;SET FLAG FOR RATE DECREASE
16B6 CD 16BA     1783           JSR   SPEED          ;GO SET SPEED AND UPDATE
16B9 81          1784           RTS
                 1785     ;
                 1786     ;          Speed control for touch panel
                 1787     ;
16BA 3C 78       1788     SPEED INC   SPEED1
16BC B6 78       1789           LDA   SPEED1
```

```
16BE A1 40      1790            CMP   #$40        ;WAIT 1.98 SEC
16C0 23 0A      1791            BLS   SPD1        ;AT FIRST SPEED
16C2 A1 90      1792            CMP   #$90        ;WAIT 3.465 SEC
16C4 23 15      1793            BLS   SPD2
16C6 A6 F0      1794            LDA   #$F0
16C8 B7 78      1795            STA   SPEED1
16CA 20 21      1796            BRA   SPD4
                1797      ;
                1798      ;         Speed 1
                1799      ;
16CC 3C 7C      1800      SPD1  INC   OUTSPD
16CE B6 7C      1801            LDA   OUTSPD
16D0 A1 0F      1802            CMP   #$0F        ;CHANGE EVERY .495 SEC
16D2 27 19      1803            BEQ   SPD4
16D4 B6 78      1804            LDA   SPEED1          ;EXCEPT FIRST TIME THROUGH
16D6 A1 01      1805            CMP   #$01
16D8 27 13      1806            BEQ   SPD4
16DA 81         1807            RTS
                1808      ;
                1809      ;         Speed 2
                1810      ;
16DB 3C 7C      1811      SPD2  INC   OUTSPD
```

```
16DD B6 7C      1812          LDA   OUTSPD
16DF A1 06      1813          CMP   #$06        ;CHANGE EVERY .198 SEC
16E1 27 0A      1814          BEQ   SPD4
16E3 81         1815          RTS
                1816    ;
                1817    ;        Speed 3
                1818    ;
16E4 3C 7C      1819    SPD3  INC   OUTSPD
16E6 B6 7C      1820          LDA   OUTSPD
16E8 A1 05      1821          CMP   #$05
16EA 27 01      1822          BEQ   SPD4
16EC 81         1823          RTS
                1824    ;
16ED 3F 7C      1825    SPD4  CLR   OUTSPD
16EF 16 6D      1826          BSET  3,PSTAT1          ;MAKE START ON
16F1 18 6D      1827          BSET  4,PSTAT1          ;TURN DISPLAY ON
16F3 00 77 06   1828          BRSET 0,CCWF,DEC1       ;IF CCW FLAG SET DEC DOSE OR RATE
                1829    ;                             ;ELSE INCREASE DOSE OR RATE
                1830    ;        INCREASE
                1831    ;
16F6 00 71 09   1832          BRSET 0,DFLAG,INCR1D          ;IF DOSE, INCREMENST DOSE
16F9 CC 131E    1833          JMP   INCR1                   ;ELSE, INCREMENT RATE
```

```
                    1834    ;
                    1835    ;       DECREMENT
                    1836    ;
16FC 00 71 28       1837    DEC1  BRSET 0,DFLAG,DECR1D          ;IF DOSE, DECREMENT DOSE
16FF CC 1365        1838          JMP     DECR1                 ;ELSE, DECREMENT RATE
                    1839    ;
                    1840
1702 B6 57          1841    INCR1D      LDA   DOSECT            ;DELAY INC TO ALLOW doSE DISPLAY
1704 A1 1F          1842          CMP   #31
1706 23 42          1843          BLS   NODOSE            ;RETURN FROM INC
1708 15 71          1844                BCLR  2,DFLAG           ;CLR DOSE 0 FLAG
170A A6 3D          1845            LDA #61         ;RESET DOSE TIMER EACH
170C B7 57          1846          STA   DOSECT            ;TIME BUTTON IS PRESSED
                    1847    ;
170E B6 56          1848          LDA   DS2         ;IF DOSE IS 2000 DONT INCREMENT
1710 A4 F0          1849          AND   #$F0        ;MASK LOWER NIBBLE TO GET MSD
1712 A1 20          1850          CMP   #$20
1714 27 97          1851          BEQ   OVER1             ;IF MSD IS 2, SKIP INCREMENT
                    1852
1716 B6 55          1853          LDA   DS1
1718 AB 05          1854          ADD   #$05        ;BINARY ADD DS1
171A 8D             1855          DAA               ;CONVERT TO BCD
```

```
171B B7 55      1856          STA   DS1
171D B6 56      1857          LDA   DS2
171F A9 00      1858          ADC   #$00        ;BINARY ADD CARRY
1721 8D         1859          DAA               ;CONVERT TO BCD
1722 B7 56      1860          STA   DS2
1724 CC 1745    1861          JMP   DSEXP             ; UPDATE DOSE
                1862    ;
                1863    ;     DECREMENT DOSE BY 1
                1864
1727 B6 57      1865    DECR1D      LDA   DOSECT          ;DELAY INC TO ALLOW doSE DISPLAY
1729 A1 1F      1866          CMP   #31
172B 23 1D      1867          BLS   NODOSE            ;RETURN FROM INC
172D A6 3D      1868                LDA   #61         ;RESET DOSE TIMER
172F B7 57      1869          STA   DOSECT          ;EACH TIME BUTTON IS PUSHED
                1870    ;
1731 B6 55      1871          LDA   DS1         ;IF DOSE IS 0 DONT DECREMENT
1733 BA 56      1872          ORA       DS2
1735 27 13      1873          BEQ   NODOSE
                1874
                1875    ;
1737 B6 55      1876          LDA   DS1
1739 AB 95      1877          ADD   #$95        ;10 COMPLIMENT BINARY SUBTRACT
```

```
173B 8D          1878          DAA             ;CONVERT RESULT TO BCD
173C B7 55       1879          STA   DS1
173E B6 56       1880          LDA   DS2
1740 A9 99       1881          ADC   #$99       ;10 COMPLIMENT BINARY SUBTRACT WITH C
1742 8D          1882          DAA             ;CONVERT TO BCD
1743 B7 56       1883          STA   DS2
                 1884     ;
1745 AE 55       1885     DSEXP LDX   #DS1          ;SET POINTER TO DS1 ADDRESS
1747 CD 19E7     1886           JSR   BCDEXP
174A 81          1887     NODOSE      RTS
                 1888     ;
                 1889     ;
                 1890     ;------------ TOGGLE DIGIT ONE ----------------------
                 1891     ;
                 1892     ;
                 1893     ;
174B 00 51 05    1894     TOGGLE      BRSET 0,DSPDG1,DEC5     ;IF 5 MAKE 0
174E A6 05       1895           LDA   #$05        ;IF 0 MAKE 5
1750 B7 51       1896           STA     DSPDG1
1752 81          1897           RTS
1753 3F 51       1898     DEC5  CLR   DSPDG1           ;
1755 81          1899           RTS
```

```
                    1900    ;
                    1901    ;
                    1902    ;       Update the digit numbers
                    1903    ;
                    1904    ;
1756 BE 51          1905    UPDATE      LDX   DSPDG1
1758 D6 101F        1906            LDA DIGITS,X
175B B7 50          1907        STA   SAMPL4
175D BE 52          1908        LDX   DSPDG2
175F D6 101F        1909        LDA   DIGITS,X
1762 B7 4F          1910        STA   SAMPL3
1764 BE 53          1911        LDX   DSPDG3
1766 D6 101F        1912        LDA   DIGITS,X
1769 B7 4E          1913        STA   SAMPL2
176B BE 54          1914            LDX DSPDG4
176D D6 101F        1915        LDA   DIGITS,X
1770 B7 4D          1916        STA   SAMPL1
                    1917    ;CHECK THIS CODE FOR HANDLING ZEROST FLAG
                    1918    ;
1772 1D 74          1919        BCLR  6,ZEROST    ;INITIALIZE ZEROST
1774 1F 74          1920        BCLR  7,ZEROST    ;AND
1776 3F 64          1921        CLR   COUNT3            ;COUNT3 FOR LED MUX ROUTINE
```

```
                    1922
                    1923    ;
1778 3F 4B          1924            CLR   HLDTIM1           ;CLEAR HLDTIM1 AND HLDTIM2
177A 3F 4C          1925            CLR   HLDTIM2           ;TO RESTART 2 1/2 MIN TIMER
                    1926                                  ;EACH TIME DISPLAY IS UPDATED
                    1927    ;
                    1928    ;
                    1929    ;                   CALCULATE MOTOR TIMES
                    1930    ;
177C 3F 67          1931            CLR   QH
177E 3F 69          1932            CLR   PH
1780 A6 0A          1933            LDA   #10
1782 B7 68          1934            STA   QL
1784 B6 52          1935            LDA   DSPDG2
1786 B7 6A          1936            STA   PL
1788 CD 196F        1937            JSR   MULT16
178B B6 51          1938            LDA   DSPDG1
178D BB 68          1939            ADD   QL
178F B7 46          1940            STA   ALGO
1791 A6 64          1941            LDA   #100
1793 B7 68          1942            STA   QL
1795 B6 53          1943            LDA   DSPDG3
```

```
1797 B7 6A      1944          STA   PL
1799 CD 196F    1945          JSR   MULT16
179C B6 46      1946          LDA   ALGO
179E B7 6A      1947          STA   PL
17A0 CD 1962    1948          JSR   ADD16
17A3 B6 67      1949          LDA   QH
17A5 B7 69      1950          STA   PH
17A7 B6 68      1951          LDA   QL
17A9 B7 6A      1952          STA   PL
17AB A6 D6      1953          LDA   #$D6
17AD B7 67      1954          STA   QH
17AF A6 E8      1955          LDA   #$E8
17B1 B7 68      1956          STA   QL
17B3 CD 1993    1957          JSR   DIV16
17B6 B6 53      1958          LDA   DSPDG3
17B8 26 09      1959          BNE   MULT3
17BA B6 65      1960          LDA   XH
17BC B7 48      1961          STA   TIMHI
17BE B6 66      1962          LDA   XL
17C0 B7 47      1963          STA   TIMLO
17C2 81         1964          RTS
                1965    ;
```

```
17C3 B6 65          1966      MULT3 LDA   XH
17C5 B7 67          1967            STA   QH
17C7 B6 66          1968            LDA   XL
17C9 B7 68          1969            STA   QL
17CB A6 03          1970            LDA   #3
17CD B7 6A          1971            STA   PL
17CF 3F 69          1972            CLR   PH
17D1 CD 196F        1973            JSR   MULT16
17D4 B6 68          1974            LDA   QL
17D6 B7 47          1975            STA   TIMLO
17D8 B6 67          1976            LDA   QH
17DA B7 48          1977            STA   TIMHI
17DC 81             1978            RTS
                    1979      ;
                    1980      ;
                    1981      $EJECT
```

```
                    1982    ;
                    1983    ;
                    1984    ;                   AC OR DC CHECK
                    1985    ;-----------------------------------------------------------------
                    1986    ;
17DD 0D 02 03       1987    ACDC  BRCLR 6,PORTC,AC      ;IF CLR ITS AC
17E0 13 6E          1988          BCLR  1,ACON          ;IF NOT CLEAR THE FLAG
17E2 81             1989          RTS
17E3 12 6E          1990    AC    BSET  1,ACON          ;SET FLAG ITS AC
                    1991    ;     CLR   T25         ;RESET TIMER FOR AUTO OFF
                    1992    ;     CLR   T20
17E5 81             1993          RTS
                    1994    ;
                    1995    $EJECT
```

```
                1996    ;
                1997    ;
                1998    ;                    BATTERY CHECK
                1999    ;-----------------------------------------------------------------
                2000    ;
17E6 02 6E 37   2001    BATCK BRSET 1,ACON,NOLOB     ;IF ON AC DONT DO
17E9 00 80 45   2002          BRSET 0,DSPTST,NLB     ;DONT DO IF TEST MODE
17EC 00 6E 1D   2003          BRSET 0,LOWBAT,LBTM    ;IF LOW ALREADY TIME 15 MIN.
17EF 03 6D 07   2004          BRCLR 1,PSTAT1,LOBCK   ;IF MOTOR OFF CHECK
17F2 B6 5B      2005          LDA   REG1             ;WAIT UNTILL MOTOR RUNS .4 SEC
17F4 A1 1E      2006          CMP   #30
17F6 22 01      2007          BHI   LOBCK
17F8 81         2008          RTS
17F9 08 02 35   2009    LOBCK BRSET 4,PORTC,NLB ;IF NO SIGNAL THEN LOW BAT
17FC 05 6D 1A   2010          BRCLR 2,PSTAT1,KILTIM ;IF PUMP IS OFF, DISABLE PUMP
17FF 10 6E      2011          BSET  0,LOWBAT    ;SET LOW BAT FLAG
1801 1E 6E      2012          BSET  7,ERRON          ;SET ERROR
1803 1A 6E      2013          BSET  5,ALRM           ;SET ALARM
1805 17 6D      2014          BCLR  3,PSTAT1    ;GET OUT OF START MODE TO ENABLE LOW BAT
1807 11 71      2015          BCLR  0,DFLAG          ;CLEAR DOSE MODE FLAG
1809 1D 6E      2016          BCLR  6,VOLM           ;CLEAR VOLUME MODE FLAG
180B 81         2017          RTS
```

```
                2018    ;
                2019    ;       INCREMENT 15 MIN TIMER
                2020    ;
180C 3C 49      2021    LBIM    INC     BATIM1          ;INCREMENT BATTERY TIMER: BATM1,BATIM2
180E 26 02      2022            BNE     CONCNT
1810 3C 4A      2023            INC     BATIM2
1812 B6 4A      2024    CONCNT  LDA     BATIM2
1814 A1 07      2025            CMP     #$07        ;IF BAT TIMER HAS COUNTED 15 MIN
1816 27 01      2026            BEQ     KILTIM          ;KILL POWER
1818 81         2027            RTS
1819 9B         2028    KILTIM      SEI             ;SET INT MASK TO PREVENT TURN-ON
181A A6 0F      2029            LDA     #$0F        ;DISABLE PUMP
181C B7 01      2030            STA     PORTB
181E 20 F9      2031            BRA     KILTIM
                2032    ;
1820 01 6E 0E   2033    NOLOB BRCLR 0,LOWBAT,NLB    ;DONT CLEAR ANY THING IF NO LOW BAT
                2034                            ;THIS MAINTAINS OTHER ERRORS IF PRESENT
1823 11 6E      2035            BCLR    0,LOWBAT    ;CLR LOW BAT FLAG
1825 1F 6E      2036            BCLR    7,ERRON         ;CLR ERROR FLAG
1827 1B 6E      2037            BCLR    5,ALRM          ;CLR ALARM
1829 18 6D      2038            BSET    4,PSTAT1    ;MAKE SURE DISPLAY ON
182B CD 1756    2039            JSR     UPDATE          ;UPDATE DISPLAY
```

```
182E CD 1948      2040          JSR   TIMRST          ;CLEAR TIMER COUNTERS
                  2041     ;
                  2042     ;    JSR   HOLD       ;COMMENTED OUT TO ALLOW MOTOR TO
                  2043     ;                     ;CONTINUE WHEN AC APPLIED.
1831 3F 49        2044     NLB  CLR   BATIM1          ;CLEAR BATTERY TIMERS
1833 3F 4A        2045          CLR   BATIM2
1835 81           2046          RTS
                  2047     ;
                  2048     $EJECT
```

```
                    2049    ;
                    2050    ;           DEAD BATTERY CHECK
                    2051    ;
                    2052    ;     This routine checks the dead battery signal (portc(7)).
                    2053    ;     If this signal is active (portc(7)=0), then the routine
                    2054    ;     kills power to the processor.
                    2055    ;-----------------------------------------------------------------------
                    2056    ;
1836 02 6E 14       2057    DBATCK      BRSET 1,ACON,NODBCK     ;DON'T DO IF AC POWERED
1839 03 6D 07       2058          BRCLR 1,PSTAT1,DEADCK ;IF MOTOR OFF CHECK
183C B6 5B          2059          LDA   REG1            ;WAIT UNTILL MOTOR RUNS .4 SEC
183E A1 1E          2060          CMP   #30
1840 22 01          2061          BHI   DEADCK
1842 81             2062          RTS
                    2063    ;
1843 0E 02 07       2064    DEADCK  BRSET    7,PORTC,NODBCK    ;IF NO DEAD BAT SIGNAL, RETURN
                    2065    ;
1846 9B             2066    DBKIL SEI               ;SET INT MASK TO PREVENT TURN-ON
1847 A6 0F          2067          LDA   #$0F        ;DISABLE PUMP
1849 B7 01          2068          STA   PORTB
184B 20 F9          2069          BRA   DBKIL       ;LOOP UNTIL POWER DISSIPATES
                    2070    ;
```

```
184D 81          NODBCK    RTS
                 ;
                 $EJECT
```

```
                        2074    ;
                        2075    ;                   ALARM
                        2076    ;-------------------------------------------------------------------
                        2077    ;       Conditions
                        2078    ;
184E 05 6D 08           2079    ALARM BRCLR 2,PSTAT1,NOALM    ;IF OFF DONT ALARM
1851 0C 6E 05           2080          BRSET 6,VOLM,NOALM      ;IF IN VOLUME DONT DO
1854 0A 6E 03           2081          BRSET 5,ALRM,ALRMRT     ;IF ALARM FLAG SET THEN ALARM
                        2082    ;
                        2083    ;
1857 1F 01              2084    ALCLR       BCLR  7,PORTB           ;SET ALARM HIGH
1859 81                 2085    NOALM RTS
185A 08 6D FA           2086    ALRMRT  BRSET     4,PSTAT1,ALCLR
185D 1E 01              2087          BSET  7,PORTB
185F 81                 2088          RTS
                        2089    ;
                        2090    $EJECT
```

```
                        2091    ;
                        2092    ;
                        2093    ;
                        2094    ;                   BLINK THE DISPLAY
                        2095    ;---------------------------------------------------------------
                        2096    ;
                        2097    ;         Conditions
                        2098    ;
1860 05 6D 26           2099    BLINK BRCLR 2,PSTAT1,NOBLIN   ;IF OFF DONT DO
1863 06 6D 23           2100          BRSET 3,PSTAT1,NOBLIN ;DONT BLINK IF START ON
1866 0E 6E 03           2101          BRSET 7,ERRON,BL1 ;GO BLINK IF ERROR MODE
1869 01 6D 35           2102          BRCLR   0,PSTAT1,DOTBL  ;DONT BLINK IN RUN
                        2103    ;
                        2104    ;         Blink
                        2105    ;
186C A6 C0              2106    BL1         LDA   #$C0              ;BLANK 4TH DIGIT
186E B7 4D              2107          STA   SAMPL1
1870 09 6D 17           2108          BRCLR 4,PSTAT1,SETBL    ;IF DISPLAY ON BLANK
1873 19 6D              2109          BCLR  4,PSTAT1
1875 0F 6E 11           2110          BRCLR 7,ERRON,NOBLIN
1878 00 6E 5A           2111          BRSET 0,LOWBAT,LO1      ;IF LO BAT ON THEN DO
187B 08 6E 71           2112          BRSET 4,NOSET,NO1 ;IF NO SET THEN DO
```

```
187E 04 6E 50    2113          BRSET 2,NDROP,FLO1    ;IF FLOW ERR THEN DO
1881 00 70 45    2114          BRSET 0,DOSER,DOSE1    ;IF DOSE ERROR THEN DO
1884 06 6E 46    2115          BRSET 3,HOLDER,HLD1    ;IF HOLD ERROR THEN DO
1887 20 59       2116          BRA   ERR1
1889 81          2117     NOBLIN       RTS
                 2118     ;
                 2119     ;          Hold mode blink
                 2120     ;
188A 18 6D       2121     SETBL BSET  4,PSTAT1          ;BLANK DISPLAY
188C 0F 6E FA    2122           BRCLR 7,ERRON,NOBLIN
188F 00 6E 54    2123           BRSET 0,LOWBAT,BAT1    ;GO DO BAT IF LO BAT
1892 08 6E 5E    2124           BRSET 4,NOSET,SET2     ;GO DO SET IF NO SET
1895 04 6E 4A    2125           BRSET 2,NDROP,ERR1     ;GO DO ERR IF FLOW ERR
1898 00 70 26    2126           BRSET 0,DOSER,OUT2     ;GO DO DEL IF DOSE ERR
189B 06 6E 44    2127           BRSET 3,HOLDER,ERR1    ;GO DO ERR IF HOLD ERR
189E 20 3E       2128           BRA   SYS1
18A0 81          2129           RTS
                 2130     ;
                 2131     ;          Blink the DP during the run mode
                 2132     ;
18A1 BE 63       2133     DOTBL LDX   COUNT2            ;GET DP #
18A3 E6 4D       2134           LDA   SAMPL1,X         ;GET NEW DIGIT
```

```
18A5 AA 80        2135          ORA   #$80          ;CLEAR DP
18A7 E7 4D        2136          STA   SAMPL1,X      ;STORE IT FOR DISPLAY
18A9 5C           2137          INCX                  ;BUMP POINTER TO NEXT DIGIT
18AA A3 04        2138          CPX   #$04          ;DONE ALL THREE
18AC 27 09        2139          BEQ   NEWX          ;RESET IF SO
18AE E6 4D        2140    DOTON LDA   SAMPL1,X      ;GET NEXT DIGIT
18B0 A4 7F        2141          AND   #$7F          ;TURN DP ON
18B2 E7 4D        2142          STA   SAMPL1,X      ;STORE IT FOR DISPLAY
18B4 BF 63        2143          STX   COUNT2        ;SAVE COUNT
18B6 81           2144          RTS
                  2145    ;
18B7 0F 6D 03     2146    NEWX  BRCLR 7,PSTAT1,DOT24   ;IF 224, SCROLL 3 DIGITS
18BA 5F           2147          CLRX                  ;RESET COUNTER
18BB 20 F1        2148          BRA   DOTON         ;GO TURN ON
                  2149    ;
18BD AE 01        2150    DOT24 LDX   #$01      ;IF THIRD DIGIT
18BF 20 ED        2151          BRA   DOTON     ;ELSE CONTINUE WITH BLINK ROUTINE
                  2152    ;
                  2153    ;       Error messages
                  2154    ;
18C1 A6 8C        2155    OUT2  LDA   #$8C
18C3 B7 4D        2156          STA   SAMPL1
```

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```
                  ;
18C5 AE 16              LDX   #$16        ;DISPLAY ?
18C7 20 2E              BRA   OUTCHR
                  ;
18C9 AE 19        DOSE1 LDX   #$19        ;DISPLAY DOSE
18CB 20 2A              BRA   OUTCHR
                  ;
                  ;
18CD AE 12        HLD1  LDX   #$12        ;POINT TO ERR MESSAGE
18CF 20 26              BRA   OUTCHR            ;GO LOAD UP DIGITS
                  ;
18D1 AE 06        FLO1  LDX   #$06              ;POINT TO FLO MESSAGE
18D3 20 22              BRA    OUTCHR           ;GO LOAD UP DIGITS
                  ;
18D5 AE 00        LO1   LDX   #$00
18D7 CD 18F7            JSR   OUTCHR
18DA 01 6D C4           BRCLR 0,PSTAT1,DOTBL    ;IF IN RUN MODE, UPDATE DP SCROLL
18DD 81                 RTS
                  ;
18DE AE 1C        SYS1  LDX   #$1C        ;DISPLAY SYS
18E0 20 15              BRA   OUTCHR
                  ;
```

```
                2179    ;
18E2 AE 09      2180    ERR1  LDX   #$09
18E4 20 11      2181          BRA   OUTCHR
                2182    ;
18E6 AE 03      2183    BAT1  LDX   #$03
18E8 CD 18F7    2184          JSR   OUTCHR
18EB 01 6D B3   2185          BRCLR 0,PSTAT1,DOTBL   ;IF IN RUN MODE, UPDATE DP SCROLL
18EE 81         2186          RTS
                2187    ;
18EF AE 0C      2188    NO1   LDX   #$0C
18F1 20 04      2189          BRA   OUTCHR
                2190    ;
18F3 AE 0F      2191    SET2  LDX   #$0F
18F5 20 00      2192          BRA   OUTCHR
                2193    ;
18F7 D6 1000    2194    OUTCHR      LDA   TABLE5,X
18FA B7 4E      2195          STA   SAMPL2
18FC 5C         2196          INCX
18FD D6 1000    2197          LDA   TABLE5,X
1900 B7 4F      2198          STA   SAMPL3
1902 5C         2199          INCX
1903 D6 1000    2200          LDA   TABLE5,X
```

```
1906 B7 50        2201          STA   SAMPL4
1908 81           2202          RTS
                  2203    ;
                  2204    $EJECT
```

```
                        2205    ;
                        2206    ;               HOLD ERROR
                        2207    ;-------------------------------------------------------------------
                        2208    ;       Conditions
                        2209    ;
1909 05 6D 21           2210    HLDER BRCLR 2,PSTAT1,NOHE     ;DONT DO IF OFF
190C 01 6D 1E           2211          BRCLR 0,PSTAT1,NOHE   ;DONT DO IF NOT IN HOLD
                        2212    ;
                        2213    ;       Test for hold error
                        2214    ;
190F 3C 4B              2215          INC   HLDTM1          ;INCREMENT HOLD COUNTER
1911 26 02              2216          BNE   CNCNT
1913 3C 4C              2217          INC   HLDTM2
1915 B6 4C              2218    CNCNT LDA   HLDTM2          ;CHECK IF 2 1/2 MIN ELAPSED
1917 A1 01              2219          CMP   #$01
1919 22 0A              2220          BHI   HLDER1          ;IF HLDTIM2 > 1, HOLDER
191B 27 01              2221          BEQ   CONCK       ;IF HLDTIM2= 1, CHECK HLDTIM1
191D 81                 2222          RTS               ;ELSE RETURN
                        2223    ;
191E B6 4B              2224    CONCK LDA   HLDTM1
1920 A1 27              2225          CMP   #$27        ;IF HLDTIM1 >= 27, HOLDER
1922 24 01              2226          BHS   HLDER1
```

```
1924 81          2227          RTS
                 2228     ;
1925 17 6D       2229     HLDER1     BCLR  3,PSTAT1    ;CLEAR START FLAG
1927 16 6E       2230          BSET  3,HOLDER    ;SET HOLD ERROR FLAG
1929 1A 6E       2231          BSET  5,ALRM           ;ALARM ON
192B 1E 6E       2232          BSET  7,ERRON          ;ERROR FLAG ON
192D 81          2233     NOHE  RTS
                 2234     ;
                 2235     $EJECT
```

```
                2236    ;
                2237    ;                       ONE DAY WAIT FOR AUTO OFF
                2238    ;-------------------------------------------------------------------------
                2239    ;       Conditions
                2240    ;
192E 04 6D 0F   2241    TIM24       BRSET   2,PSTAT1,KEEPON     ;IF UNIT ON DONT DO
                2242    ;
                2243    ;       24HR TURN OFF
                2244    ;
1931 3C 45      2245            INC     T25             ;GET COUNTER
1933 B6 45      2246            LDA     T25
1935 A1 EF      2247            CMP     #$EF            ;(EF + 1) = 240 x 6 = 24 HOURS
1937 25 07      2248            BLO     KEEPON
                2249    ;
1939 9B         2250    KILLP   SEI                     ;SET INT MASK TO PREVENT TURN-ON
193A A6 0F      2251            LDA     #$0F            ;DISABLE PUMP
193C B7 01      2252            STA     PORTB
193E 20 F9      2253            BRA     KILLP           ;LOOP UNTIL POWER DISSAPTES
                2254    ;
1940 81         2255    KEEPON      RTS
                2256    ;
                2257    ;
```

```
                    2258    ;           CLEAR VOLUME SUBROUTINE
                    2259    ;     This routine is called by tim24 and ckclr routines.
                    2260    ;-------------------------------------------------------------------
                    2261    ;
1941 3F 58          2262    CLVOL CLR   DECML1
1943 3F 59          2263          CLR       VS1
1945 3F 5A          2264          CLR   VS2
1947 81             2265          RTS
                    2266    ;
                    2267    ;                   CLEAR TIMER COUNTERS
                    2268    ;-------------------------------------------------------------------
                    2269    ;
1948 3F 40          2270    TIMRST      CLR   TS
194A 3F 41          2271          CLR   T5
194C 3F 42          2272          CLR   T10
194E 3F 43          2273          CLR   T15
1950 81             2274          RTS
                    2275    ;           COMPARE DOSE TO VOLUME
                    2276    ;-------------------------------------------------------------------
                    2277    ;
                    2278    ;     IF VOLUME DELIVERED >= PROGRAMMED DOSE, SET X REGISTOR TO FF
                    2279    ;
```

```
1951 5F          2280    CPVTOD      CLRX
1952 B6 5A       2281            LDA VS2
1954 B1 56       2282        CMP   DS2
1956 25 09       2283        BLO   VLTD        ;IF VOLUME < DOSE, CLEAR C
1958 22 06       2284        BHI   VGTD              ;IF VOLUME > DOSE, SET C
                 2285    ;                       ;ELSE, CHECK VS1
195A B6 59       2286        LDA   VS1
195C B1 55       2287        CMP   DS1
195E 25 01       2288        BLO   VLTD              ;IF VOLUME < DOSE, CLEAR C
                 2289    ;
1960 53          2290    VGTD  COMX              ;SET X TO FF
1961 81          2291    VLTD    RTS
                 2292    ;
                 2293    ;
                 2294    $EJECT
```

```
2295    ;*************************************************************************
2296    ;                                                                        *
2297    ;                                                                        *
2298    ;                    MATH UTILITIES FOLLOW                               *
2299    ;                                                                        *
2300    ;                                                                        *
2301    ;*************************************************************************
2302    ;
2303    ;
2304    ;*************************************************************************
2305    ;                                                                        *
2306    ;  PROGRAM ADDS 2, 16-BIT UNSIGNED BINARY NUMBERS, PRODUCING A 17-BIT    *
2307    ; RESULT.                                                                *
2308    ;          ENTER WITH:  2, UNSIGNED 16-BIT OPERANDS TO BE ADDED IN       *
2309    ;                       PH , PL and QH , QL.                             *
2310    ;          EXIT WITH:   17-BIT RESULT IN:   CARRY , QH, QL              *
2311    ;                       (QH, QL DESTROYED).                              *
2312    ;                                                                        *
2313    ;*************************************************************************
2314    ;
2315    ;
1962 B6 68      2316    ADD16  LDA    QL      ;ADD LS BYTES.
```

```
1964 BB 6A      2317            ADD     PL
1966 B7 68      2318            STA     QL
1968 B6 67      2319            LDA     QH      ;ADD MS BYTES.
196A B9 69      2320            ADC     PH
196C B7 67      2321            STA     QH      ;16-BIT RESULT IN QH, QL.  OVERFLOW IN CARRY.
                2322    ;
196E 81         2323            RTS
                2324    ;
                2325    ;
                2326    ;
                2327    ;
                2328    ;*************************************************************************
                2329    ;                                                                       *
                2330    ;  PROGRAM MULTIPLIES 2, 16 BIT UNSIGNED BINARY OPERANDS, CREATING A 32-*
                2331    ; BIT UNSIGNED RESULT. (NO OVERFLOW IS POSSIBLE).                       *
                2332    ;               ENTER WITH:  OPERANDS TO BE MULTIPLIED IN:              *
                2333    ;                                                       QH , QL   *   *
                2334    ;                                                   and PH , PL   *
                2335    ;               EXIT WITH:   32-BIT RESULT IN:    XH , XL , QH , QL   *
                2336    ;                                                                       *
                2337    ;*************************************************************************
                2338    ;
```

```
                2339    ;
196F AE 10      2340    MULT16 LDX    #16     ;LOOP COUNTER.
1971 3F 65      2341           CLR    XH      ;CLEAR UPPER 16 BITS OF 32-BIT ACCUM.
1973 3F 66      2342           CLR    XL
1975 36 67      2343           ROR    QH      ;CHECK BIT 0 OF QL.
1977 36 68      2344           ROR    QL
1979 24 0C      2345    NXT    BCC    ROTAT   ;IF 0, DON'T ADD, JUST SHIFT.
197B B6 66      2346           LDA    XL      ;OTHERWISE, ADD IN THE CONTENTS OF PH , PL TO
197D BB 6A      2347           ADD    PL      ;XH , XL.
197F B7 66      2348           STA    XL
1981 B6 65      2349           LDA    XH
1983 B9 69      2350           ADC    PH
1985 B7 65      2351           STA    XH
                2352    ;
1987 36 65      2353    ROTAT  ROR    XH      ;SHIFT THE 32-BIT ACCUM. 1 BIT RIGHT.
1989 36 66      2354           ROR    XL
198B 36 67      2355           ROR    QH
198D 36 68      2356           ROR    QL
                2357    ;
198F 5A         2358           DECX           ;DO AGAIN IF NOT DONE WITH ALL 16 BITS.
1990 26 E7      2359           BNE    NXT
                2360    ;
```

```
1992 81          2361          RTS             ;OTHERWISE, RETURN WITH RESULT IN XH,XL,QH,QL.
                 2362      ;
                 2363      ;
                 2364      ;*************************************************************************
                 2365      ;                                                                        *
                 2366      ;  PROGRAM PERFORMS THE DIVISION OF 2, 16 BIT UNSIGNED OPERANDS, PRODUC-*
                 2367      ; ING A 16 BIT UNSIGNED RESULT:                                         *
                 2368      ;                                                                        *
                 2369      ;                 (QH , QL/ PH , PL) -----> XH , XL                      *
                 2370      ;                                                                        *
                 2371      ;               ENTER WITH: 16 BIT DIVISOR IN   PH , PL                  *
                 2372      ;                           16 BIT DIVIDEND IN  QH , QL                  *
                 2373      ;                                                                        *
                 2374      ;               EXIT WITH:  QUOTIENT TRUNCATED TO 16 BITS                *
                 2375      ;                           IN XH , XL                                   *
                 2376      ;               REGISTERS AFFECTED: X, A, COUNT1, TEMPA, TEMPX           *
                 2377      ;                           (QH, QL, PH, PL DESTROYED)                   *
                 2378      ;                                                                        *
                 2379      ;*************************************************************************
                 2380      ;
                 2381      ;
1993 A6 01       2382      DIV16  LDA    #1
```

```
1995 3D 69      2383            TST     PH
1997 2B 0B      2384            BMI     DIV153  ;IF DIVISOR IS LEFT-JUSTIFIED.
1999 4C         2385    DIV151  INCA            ;OTHERWISE, KEEP SHIFTING DIVISOR LEFT
199A 38 6A      2386            ASL     PL      ;UNTIL THE MSB IN PH = 1, OR UNTIL
199C 39 69      2387            ROL     PH      ;16 SHIFTS HAVE BEEN DONE.
199E 2B 04      2388            BMI     DIV153
19A0 A1 11      2389            CMP     #17
19A2 26 F5      2390            BNE     DIV151
19A4 B7 62      2391    DIV153  STA     COUNT1  ;COUNT1 = # SHIFTS REQUIRED +1.
19A6 B6 67      2392            LDA     QH      ;MOVE THE DIVIDEND INTO A, X.
19A8 BE 68      2393            LDX     QL
19AA 3F 67      2394            CLR     QH      ;MAKE WAY FOR THE QUOTIENT.
19AC 3F 68      2395            CLR     QL
19AE BF 6C      2396    DIV163  STX     TEMPX   ;STORAGE FOR THE DIVIDEND AFTER SUBTRACTING
19B0 B7 6B      2397            STA     TEMPA   ;OUT DIVISOR.
19B2 9F         2398            TXA
19B3 B0 6A      2399            SUB     PL      ;TRY SUBTRACTING THE DIVISOR.
19B5 B7 6C      2400            STA     TEMPX
19B7 B6 6B      2401            LDA     TEMPA   ;SAVE THE REMAINDER IN TEMPA, TEMPX.
19B9 B2 69      2402            SBC     PH
19BB B7 6B      2403            STA     TEMPA
19BD BE 6C      2404            LDX     TEMPX
```

```
19BF 24 10      2405            BCC     DIV165  ;IF CARRY=0, THEN DIVISOR WAS SMALLER THAN
                2406    ;                       ;DIVIDEND. GO SET THE CURRENT QUOTIENT BIT.
                2407    ;                       ;OTHERWISE, ADD THE DIVISOR BACK IN,
19C1 9F         2408            TXA
19C2 BB 6A      2409            ADD     PL
19C4 B7 6C      2410            STA     TEMPX
19C6 B6 6B      2411            LDA     TEMPA
19C8 B9 69      2412            ADC     PH
19CA B7 6B      2413            STA     TEMPA   ;AND SAVE IT.
19CC BE 6C      2414            LDX     TEMPX
19CE 98         2415            CLC             ;THE QUOTIENT BIT WILL BE 0.
19CF 20 01      2416            BRA     DIV167
19D1 99         2417    DIV165  SEC             ;THE QUOTIENT BIT WILL BE 1.
19D2 39 68      2418    DIV167  ROL     QL      ;ROTATE THE QUOTIENT LEFT 1 BIT,
19D4 39 67      2419            ROL     QH      ;SHIFTING THE MOST RECENT QUOTIENT BIT
19D6 34 69      2420            LSR     PH      ;INTO THE LSB.
19D8 36 6A      2421            ROR     PL
19DA 3A 62      2422            DEC     COUNT1  ;KEEP GOING UNTIL THE COUNTER=0.
19DC 26 D0      2423            BNE     DIV163
19DE B6 67      2424            LDA     QH      ;WHEN DONE, MOVE THE RESULT INTO XH, XL.
19E0 B7 65      2425            STA     XH
19E2 B6 68      2426            LDA     QL
```

```
19E4 B7 66      2427            STA     XL
                2428    ;
19E6 81         2429            RTS             ;RETURN.
                2430
                2431    ;*************************************************************************
                2432    ;                                                                       *
                2433    ;                       BCDEXP
                2434    ;
                2435    ;  PROGRAM CONVERTS 2 BYTE BCD NUMBER POINTED TO BY THE X REGISTOR  TO  *
                2436    ; A 4 BYTE DECIMAL NUMBER. THE FOUR BYTE NUMBER IS CONVERTED ON THE FLY *
                2437    ; TO THE CORRECT LED DISPLAY SEGMENT CODE WHICH IS SENT TO THE DISPLAY  *
                2438    ; BY THE LED MUX ROUTINE.                                               *
                2439    ;                                                                       *
                2440    ;               ENTER WITH: ADDRESS OF LOWER BCD BYTE IN X              *
                2441    ;                                                                       *
                2442    ;               EXIT WITH:  LED DISPLAY CODE FOR 4 DECIMAL DIGITS       *
                2443    ;                           IN SAMPL1, SAMPL2, SAMPL3, SAMPL4           *
                2444    ;                                                       *
                2445    ;               REGISTERS AFFECTED: X, A, SAMPL1 - SAMPL4, TEMPX        *
                2446    ;                                                                       *
                2447    ;*************************************************************************
                2448
```

```
19E7 BF 6C      2449    BCDEXP    STX   TEMPX          ;STORE POINTER FOR LATER USE
19E9 F6         2450              LDA   ,X            ;GET LOWER BYTE OF BCD DIGIT
19EA A4 0F      2451              AND   #$0F          ;MASK UPPER NIBBLE
19EC 97         2452              TAX
19ED D6 101F    2453              LDA   DIGITS,X      ;CONVERT DECIMAL TO LED CODE
19F0 B7 50      2454              STA   SAMPL4
                2455    ;
19F2 BE 6C      2456              LDX   TEMPX         ;RESTORE FIRST BCD BYTE
19F4 F6         2457              LDA   ,X
19F5 44         2458              LSRA
19F6 44         2459              LSRA
19F7 44         2460              LSRA
19F8 44         2461              LSRA                ;PUSH UPPER NIBBLE TO LOWER NIBBLE
19F9 97         2462              TAX
19FA D6 101F    2463              LDA   DIGITS,X      ;CONVERT DECIMAL TO LED CODE
19FD B7 4F      2464              STA   SAMPL3
                2465    ;
19FF 3C 6C      2466              INC   TEMPX         ;SET POINTER TO UPPER BCD DIGIT
1A01 BE 6C      2467                    LDX   TEMPX       ;GET SECOND BCD DIGIT
1A03 F6         2468              LDA   ,X
1A04 A4 0F      2469              AND   #$0F          ;MASK UPPER NIBBLE
1A06 97         2470              TAX
```

```
1A07 D6 101F    2471          LDA   DIGITS,X    ;CONVERT DECIMAL TO LED CODE
1A0A B7 4E      2472          STA   SAMPL2
                2473    ;
1A0C BE 6C      2474          LDX   TEMPX       ;RESTORE SECOND BCD DIGIT
1A0E F6         2475          LDA   ,X
1A0F 44         2476          LSRA
1A10 44         2477          LSRA
1A11 44         2478          LSRA
1A12 44         2479          LSRA              ;PUSH UPPER NIBBLE TO LOWER NIBBLE
1A13 97         2480          TAX
1A14 D6 101F    2481          LDA   DIGITS,X    ;CONVERT DECIMAL TO LED CODE
1A17 B7 4D      2482          STA   SAMPL1
                2483    ;
                2484    ;     UPDATE DISPLAY FLAGS USED BY LED MUX
                2485    ;
1A19 1D 74      2486          BCLR  6,ZEROST    ;CLEAR MSD ZERO FLAG
1A1B 1F 74      2487          BCLR  7,ZEROST    ;CLEAR MSD-1 ZERO FLAG
1A1D 3F 64      2488          CLR   COUNT3            ;CLEAR MUX COUNTER
1A1F 81         2489          RTS
                2490    ;
                2491    $EJECT
```

```
                    2492
        =1C00       2493            ORG   PMPTST
                    2494
1C00 1E 01          2495      ELOOP BSET  7,PORTB
1C02 20 FC          2496            BRA   ELOOP
                    2497      ;
                    2498            END
```

FIG.1

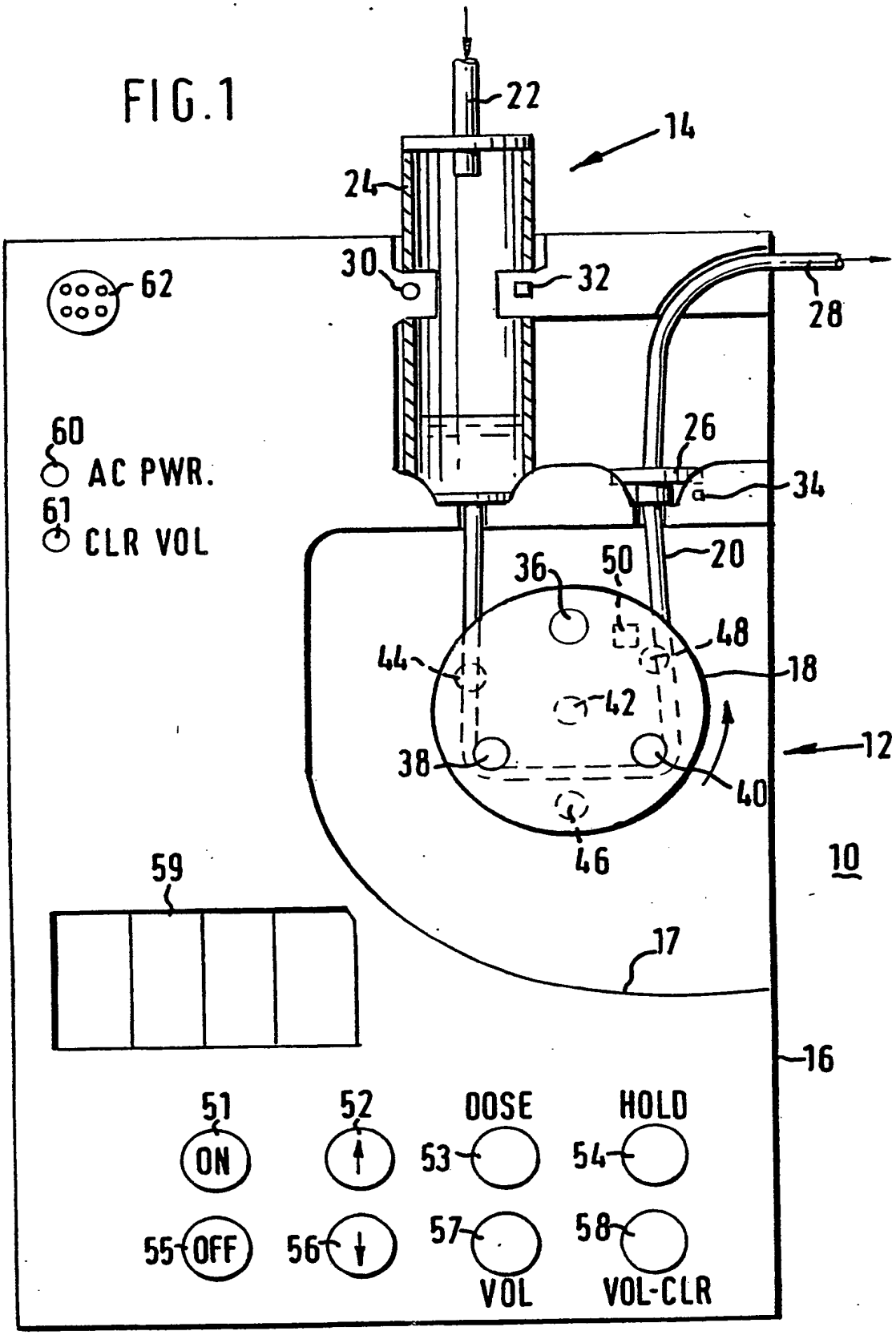

22
14
24
30
32
28
62
60
AC PWR.
61
CLR VOL
26
34
36
50
20
48
44
18
42
12
38
40
46
10
59
17
16
51
52
OOSE
HOLD
ON
53
54
55
OFF
56
57
58
VOL
VOL-CLR

FIG.2a

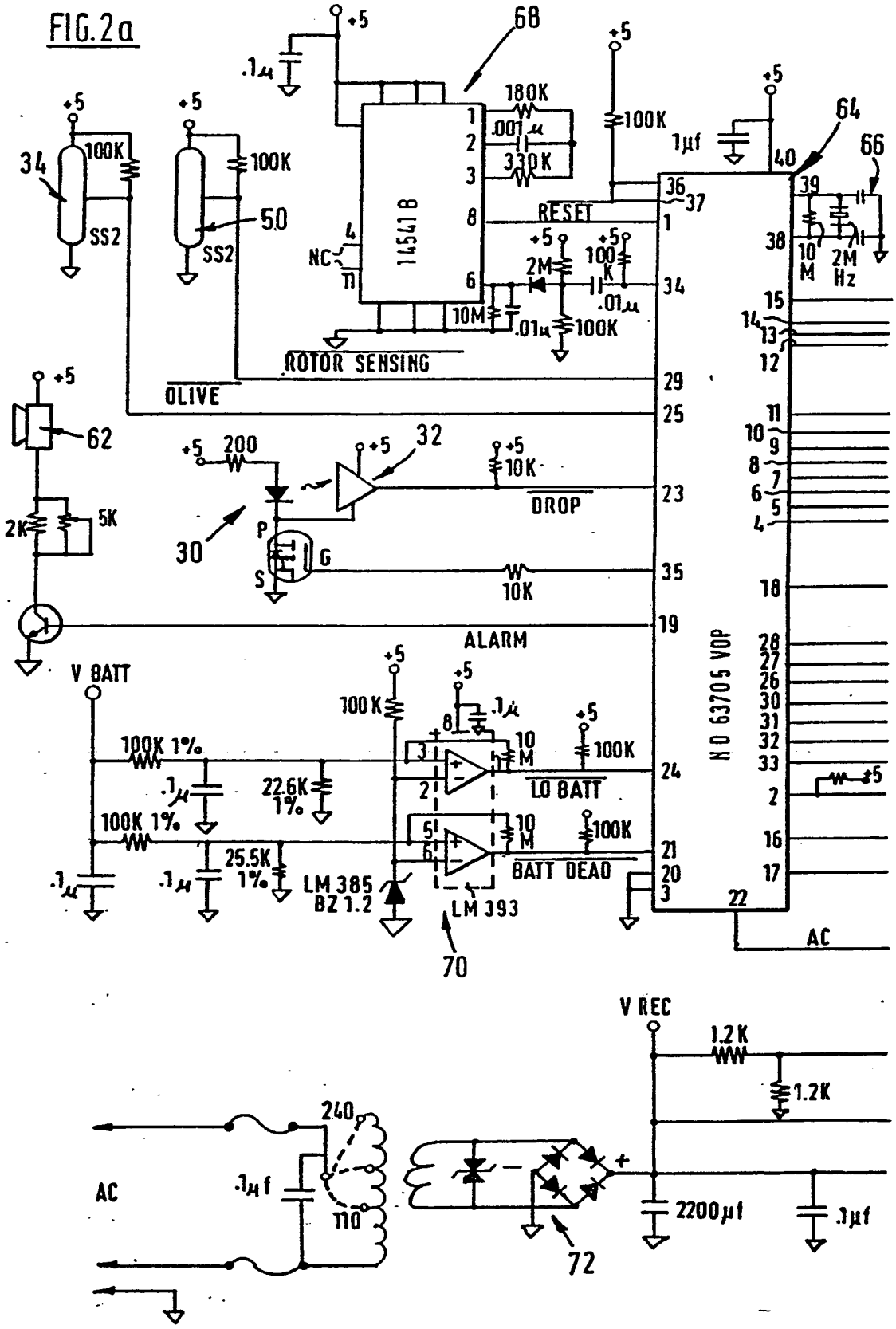

+5
.1μ
68
180K
.001μ
330K
100K
1μf
64
66
34
100K
SS2
50
14541B
RESET
2M
.01μ
10M
ROTOR SENSING
OLIVE
62
2K
5K
200
32
10K
DROP
30
P
G
S
ALARM
V BATT
100K 1%
22.6K 1%
25.5K 1%
LM 385 BZ 1.2
LM 393
LO BATT
BATT DEAD
70
NO 6370S VOP
AC
V REC
1.2K
240
110
.1μf
2200μf
72

FIG. 2b

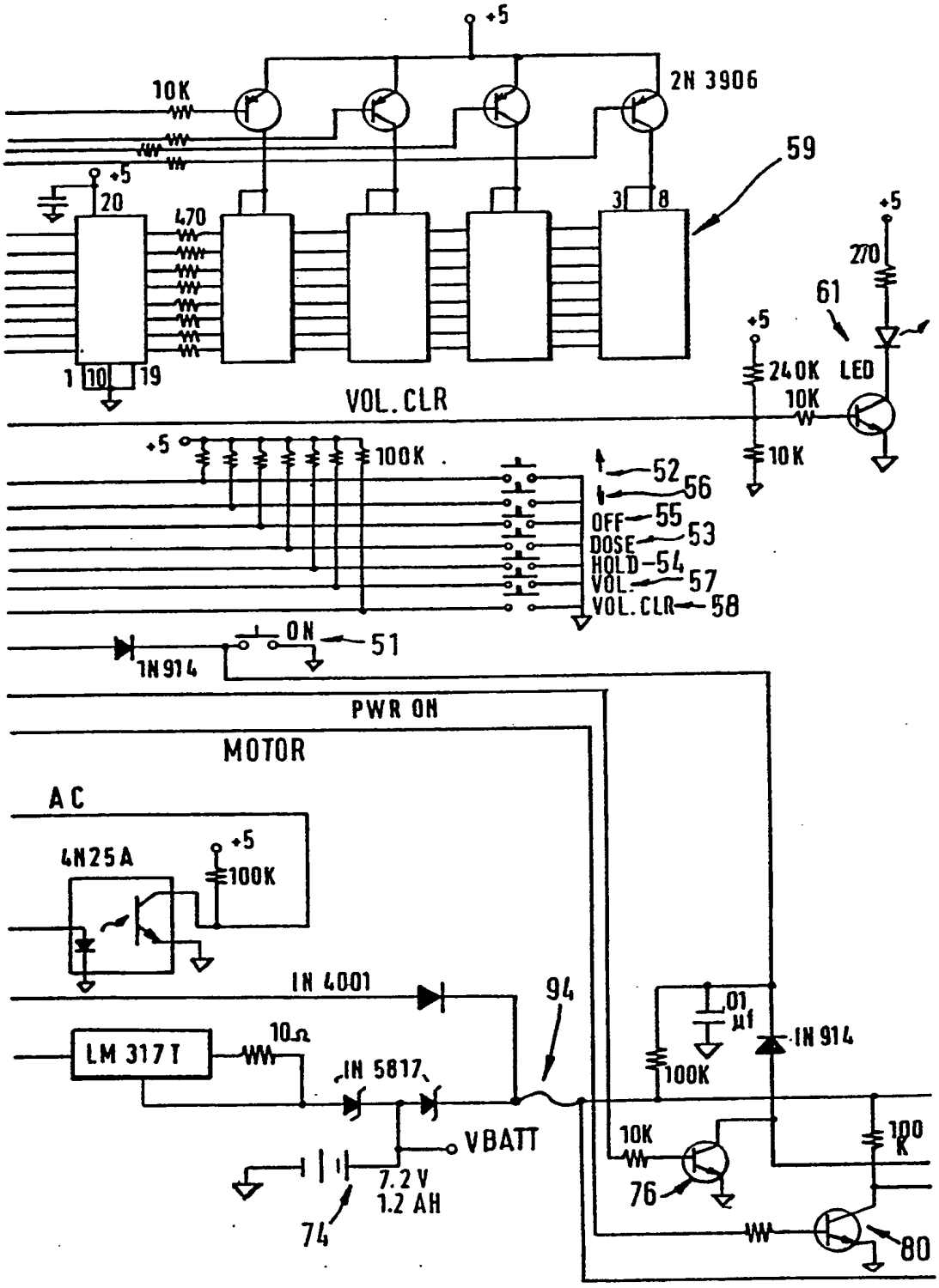
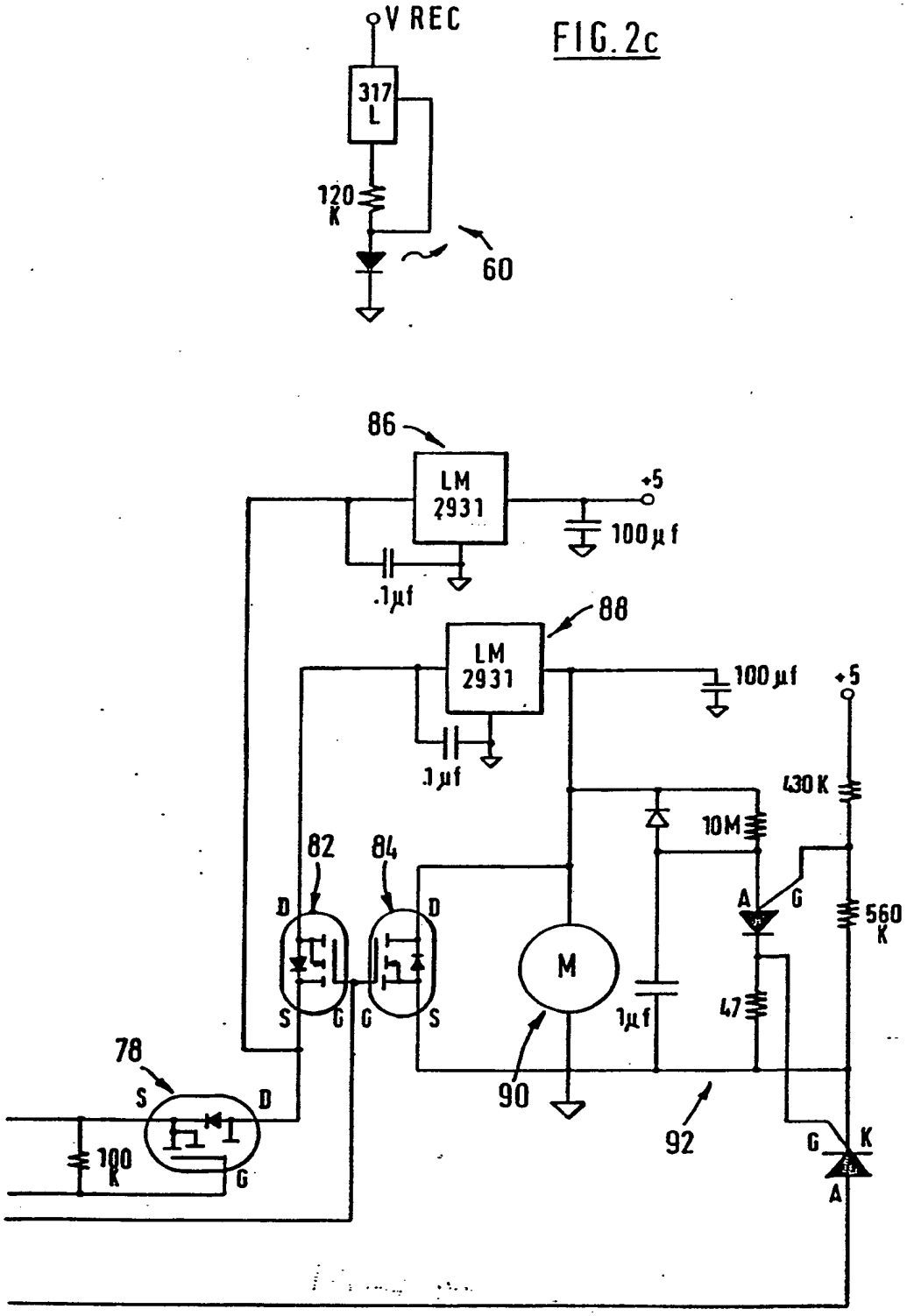


FIG. 2c


V REC
317 L
120 K
60
86
LM 2931
+5
100 µf
.1µf
88
LM 2931
100 µf
+5
.1 µf
430 K
10M
82
84
D
S
G
G
S
D
A
G
560 K
M
1µf
47
78
S
D
100 K
G
90
92
G
K
A

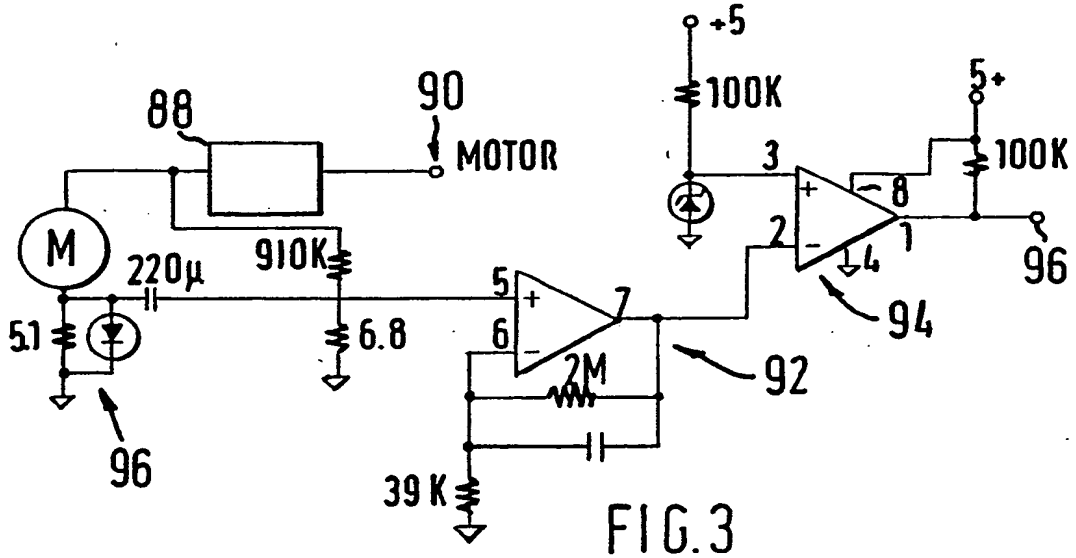


FIG.3

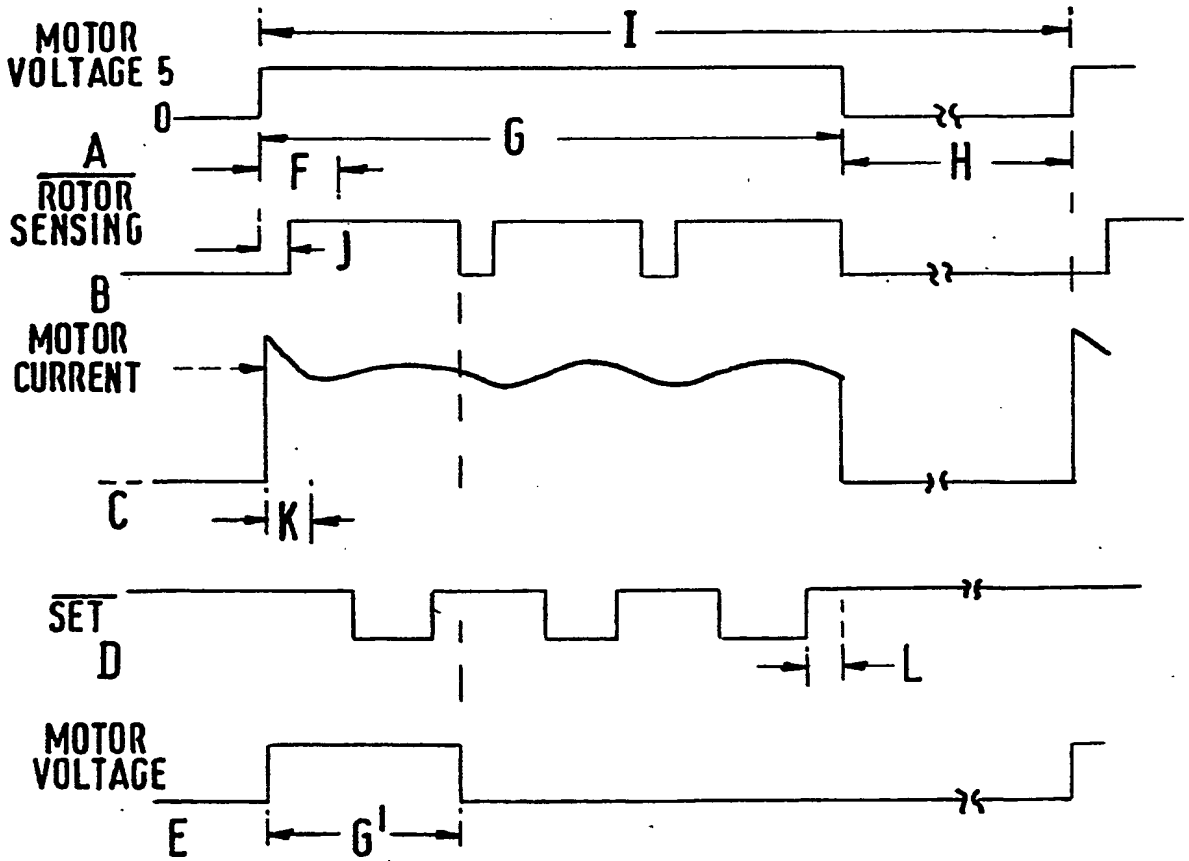


FIG 4

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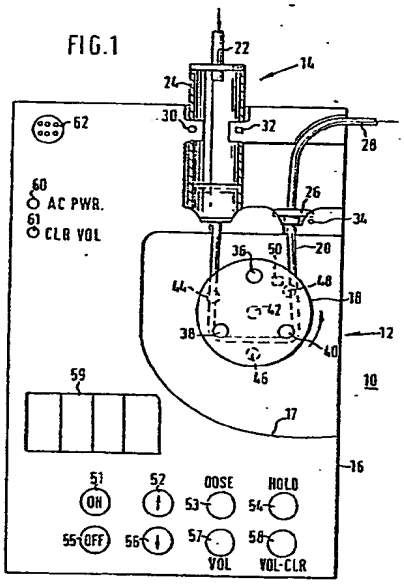
(54) **Motor unit for a fluid pump and method of operation.**

(57) An enteral nutrition pump system (10) operates in a cyclical manner with a period between cycles being selected in accordance with the desired fluid delivery rate. Each pump cycle may correspond to a single rotation of the rotor (18) or a fractional rotation of the rotor. Rotor rotation may alternatively be sensed by utilization of magnetic sensors (50) or by monitoring of the AC component of current supplied to a DC motor driving the rotor.

FIG.1



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EUROPEAN SEARCH REPORT

Application number

EP 89 30 0296

DOCUMENTS CONSIDERED TO BE RELEVANT

Category	Citation of document with indication, where appropriate, of relevant passages	Relevant to claim	CLASSIFICATION OF THE APPLICATION (Int Cl.4)
X	DE-A-2 651 962 (SIEMENS AG) * Page 10, line 22 - page 11, line 5, line 25 - page 12, line 15; figure 3 *	1-4,6, 8-11	A 61 M 5/14 F 04 B 51/00
Y	--	12	
X	EP-A-0 127 346 (PERITRONIC) * Page 8, line 10 - page 10, line 22 *	1-3,8, 9	
Y	--	12	
X	US-A-4 498 843 (SCHNEIDER et al.) * Abstract; column 9, line 44 - column 11, line 34 *	1-3,8, 9	
	--		
X	WO-A-86 01 413 (SCHWEIZER) * Claims 1-5; abstract *	1-3	TECHNICAL FIELDS SEARCHED (Int Cl.4) A 61 M H 02 P F 04 B
	--		
X	GB-A-2 011 652 (NIKKISO CO. LTD) * Page 3, lines 36-75 *	1,2	
	--		
A	EP-A-0 090 152 (SGS-ATES) * Abstract; figure 4 *	5,7,13	
	--		
A	US-A-3 610 779 (HUBBY) * Column 4, line 62 - column 5, line 71; figures 4,5 *	5,7,13, 15	

The present search report has been drawn up for all claims

Place of search	Date of completion of the search	Examiner
THE HAGUE	02-08-1989	CLARKSON

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CLAIMS INCURRING FEES

The present European patent application comprised at the time of filing more than ten claims.

☐ All claims fees have been paid within the prescribed time limit. The present European search report has been drawn up for all claims.

☐ Only part of the claims fees have been paid within the prescribed time limit. The present European search report has been drawn up for the first ten claims and for those claims for which claims fees have been paid.

namely claims:

☐ No claims fees have been paid within the prescribed time limit. The present European search report has been drawn up for the first ten claims.

X LACK OF UNITY OF INVENTION

The Search Division considers that the present European patent application does not comply with the requirement of unity of invention and relates to several inventions or groups of inventions.

namely:

1. Claims 1-4,6,8-12: Pump control involving magnetic sensing

2. Claims 1-3,5,7,13-15: Pump control involving current sensing of DC motor

☒ All further search fees have been paid within the fixed time limit. The present European search report has been drawn up for all claims.

☐ Only part of the further search fees have been paid within the fixed time limit. The present European search report has been drawn up for those parts of the European patent application which relate to the inventions in respect of which search fees have been paid,

namely claims:

☐ None of the further search fees has been paid within the fixed time limit. The present European search report has been drawn up for those parts of the European patent application which relate to the invention first mentioned in the claims,

namely claims:

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